

Introduction to machine learning and deep learning

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CURS EN VEHICLE INTEL·LIGENT

I OPORTUNITATS DE NEGOCI

**Tecnologies, reptes i oportunitats
per a la mobilitat sostenible**

Organitzadors:

CSIC
IRISA
UPPA

Parc de Recerca
UAB



Amb la col·laboració:

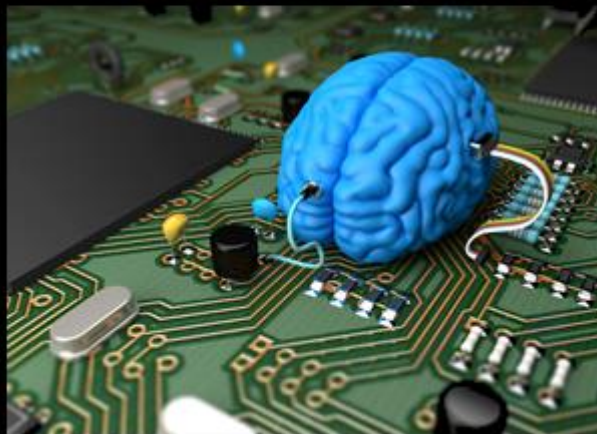
catalunya
empren



Deep Learning



What society thinks I do



What my friends think I do



What other computer scientists think I do



What mathematicians think I do

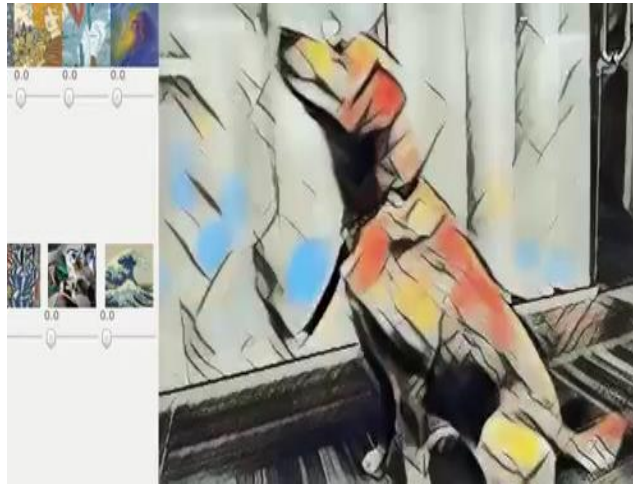


What I think I do

```
In [1]:  
import keras  
Using TensorFlow backend.
```

What I actually do

(Some) deep learning applications



Style transfer



Autonomous driving



Robotics



Music composition

Today's plan

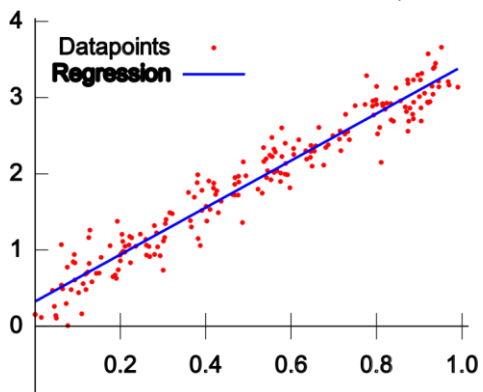
- Machine learning
- Neural networks
- Deep learning in computer vision
- Fun stuff

Today's plan

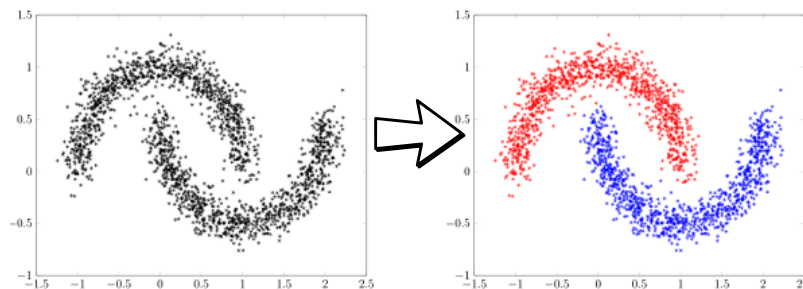
- Machine learning
 - Basic concepts
 - A toy example
- Neural networks
- Deep learning in computer vision
- Fun stuff

ML problems (according to output)

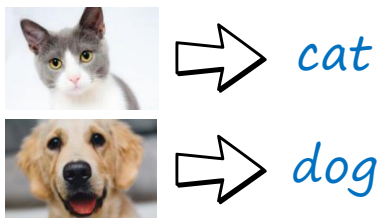
Regression
(real valued output)



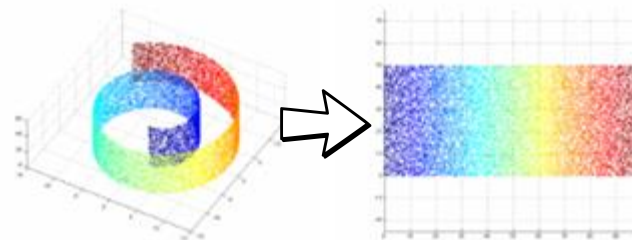
Clustering
(find groups in the data)



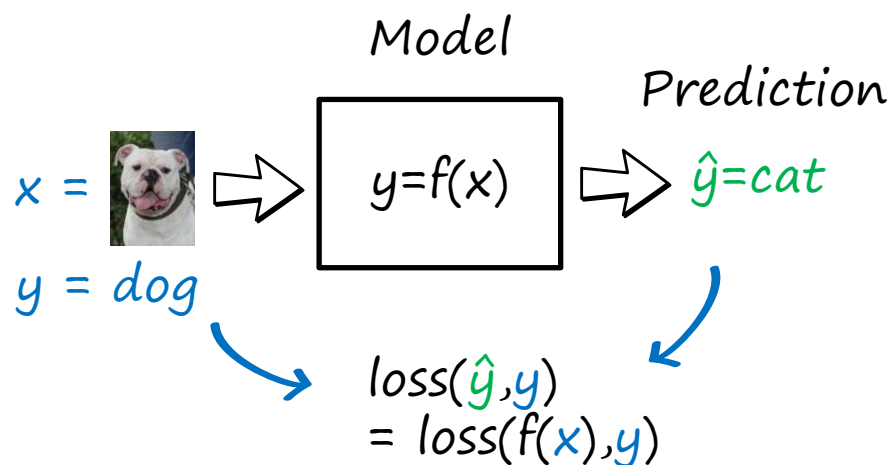
Classification
(discrete output)



Dimensionality reduction
($\dim(\text{input}) > \dim(\text{output})$)



Machine learning in a nutshell

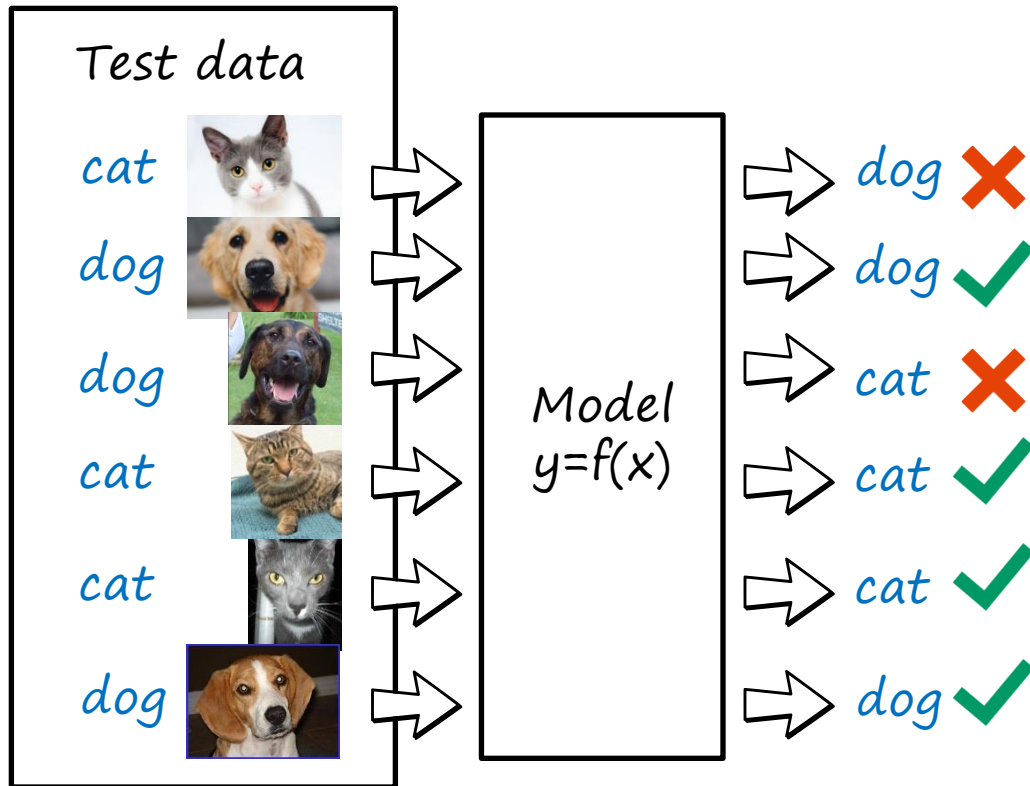


Objective: loss function
(how good/bad our prediction is)

Learning/training

We want to optimize the objective: minimize the average loss in the dataset

Evaluation



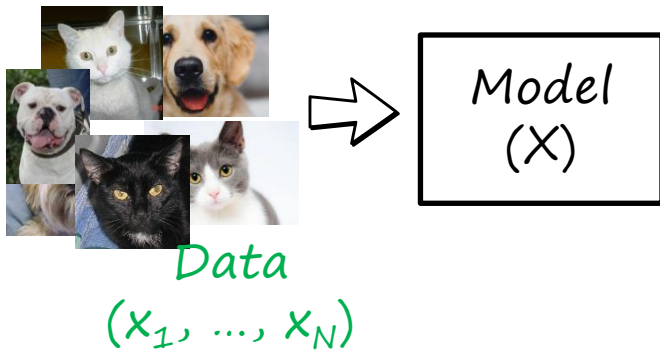
Accuracy = 4/6 = 66.7%

For a fair comparison:
training set and test set
are disjoint (no cheating
please!)

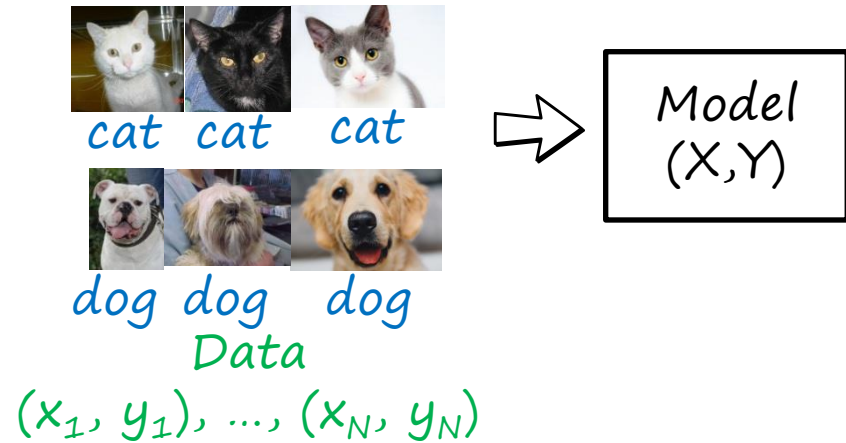


Learning paradigms

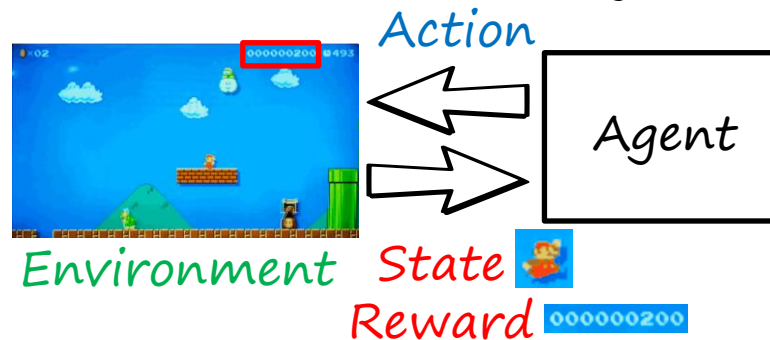
Unsupervised



Supervised



Reinforcement learning



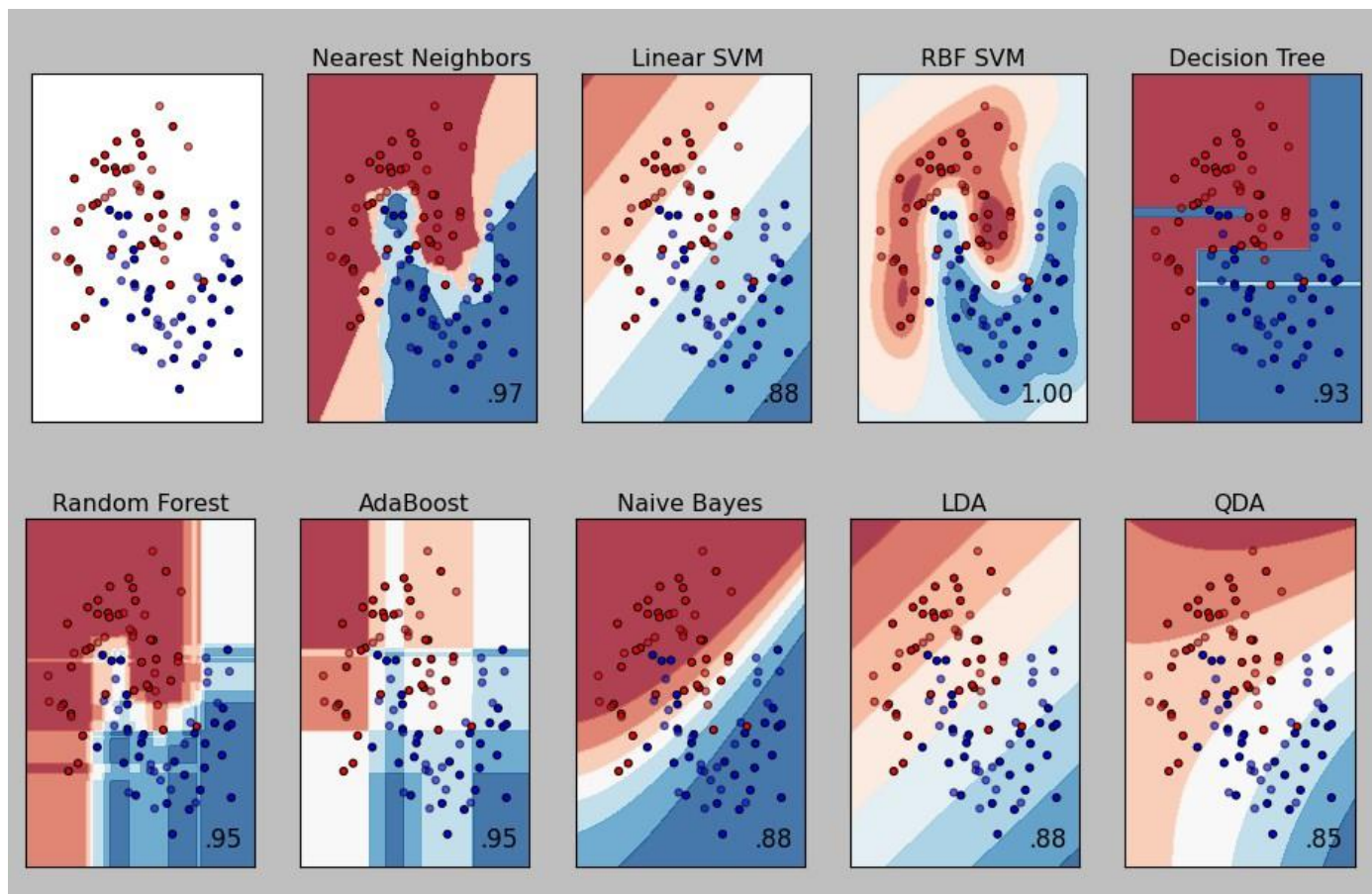
Machine learning applications

- Computer vision
- Autonomous vehicles
- Natural language processing (NLP)
- Speech recognition
- Translation
- Unmanned aerial vehicles (UAV)
- Planning
- Decision taking
- Data mining
- Product recommendation
- ...

Machine learning zoo

- Clustering
- Rule-based learning
- Decision trees and random forests
- Bayesian learning
- Boosting
- Ensemble learning
- Matrix factorization
- Genetic and evolutionary algorithms
- Support vector machines
- Kernel methods
- Artificial neural networks
 - Deep learning
- ...

Machine learning zoo



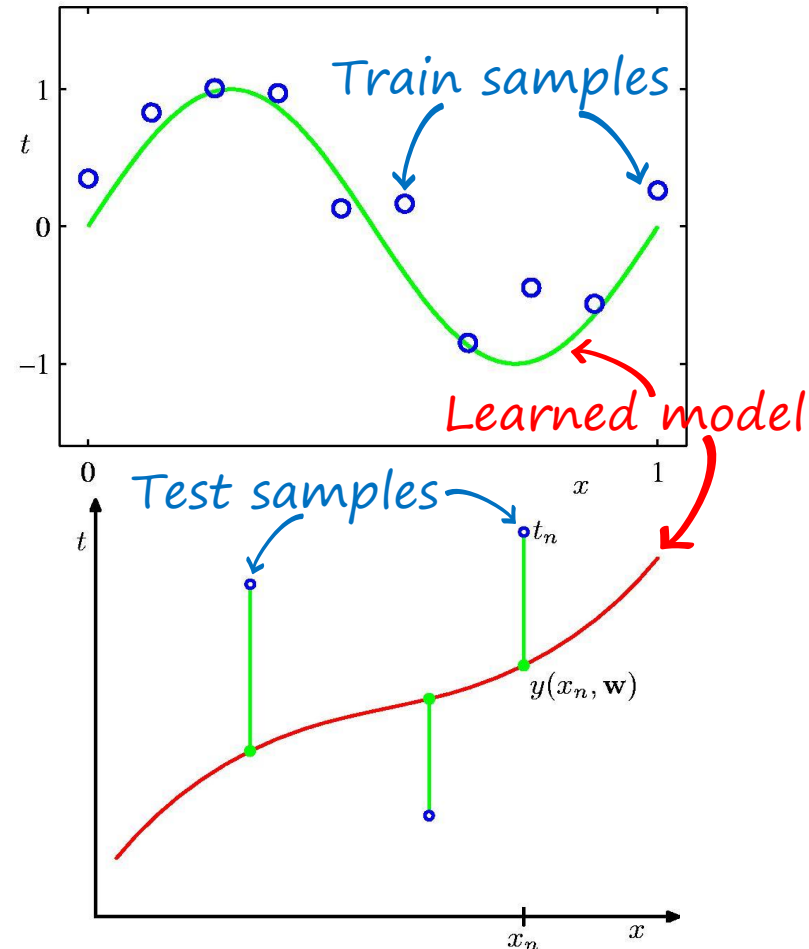
Toy example: fitting a curve

- Data: 2-D points
- Regression problem
- Model: polynomial curve

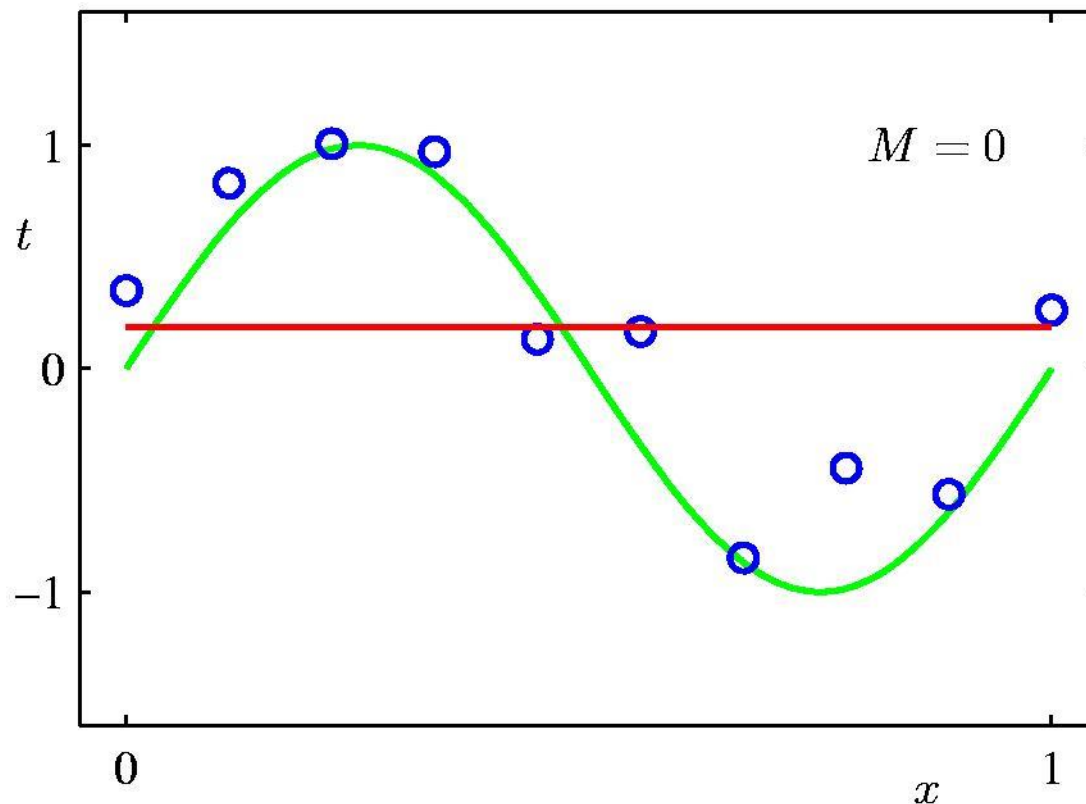
$$y(x, \mathbf{w}) = w_0 + w_1x + w_2x^2 + \dots + w_Mx^M = \sum_{j=0}^M w_jx^j$$

- Error function:
 - Sum-of-Squares

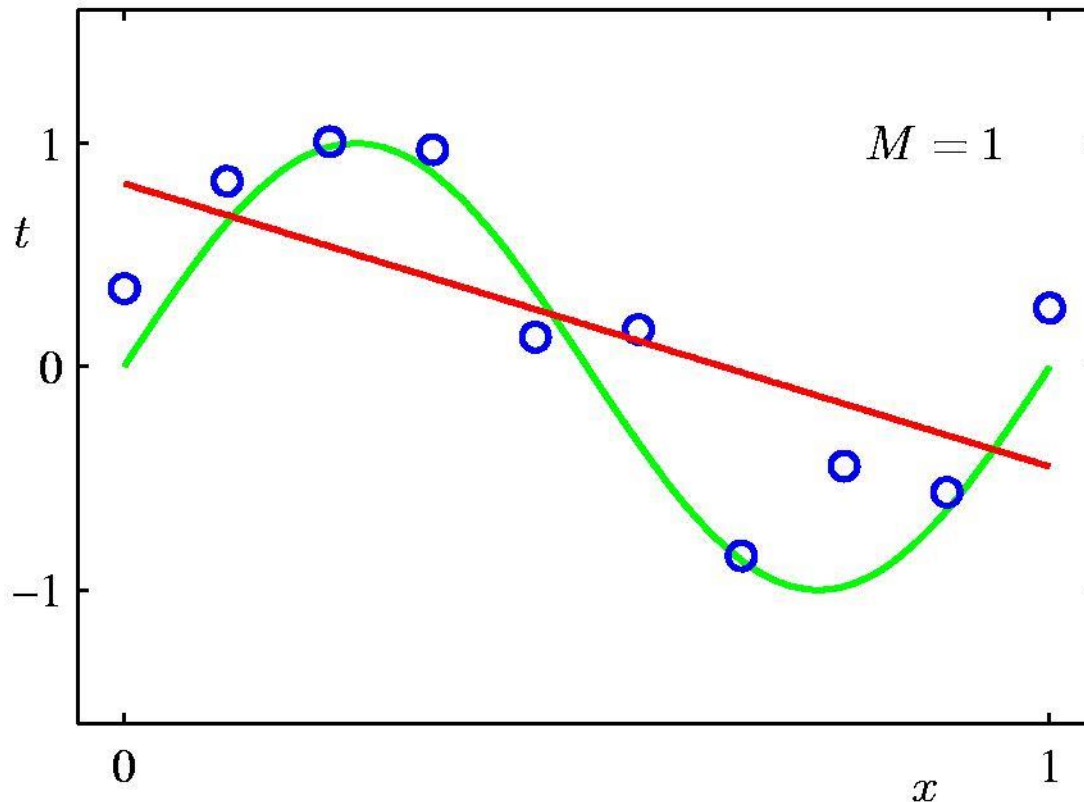
$$E(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2$$



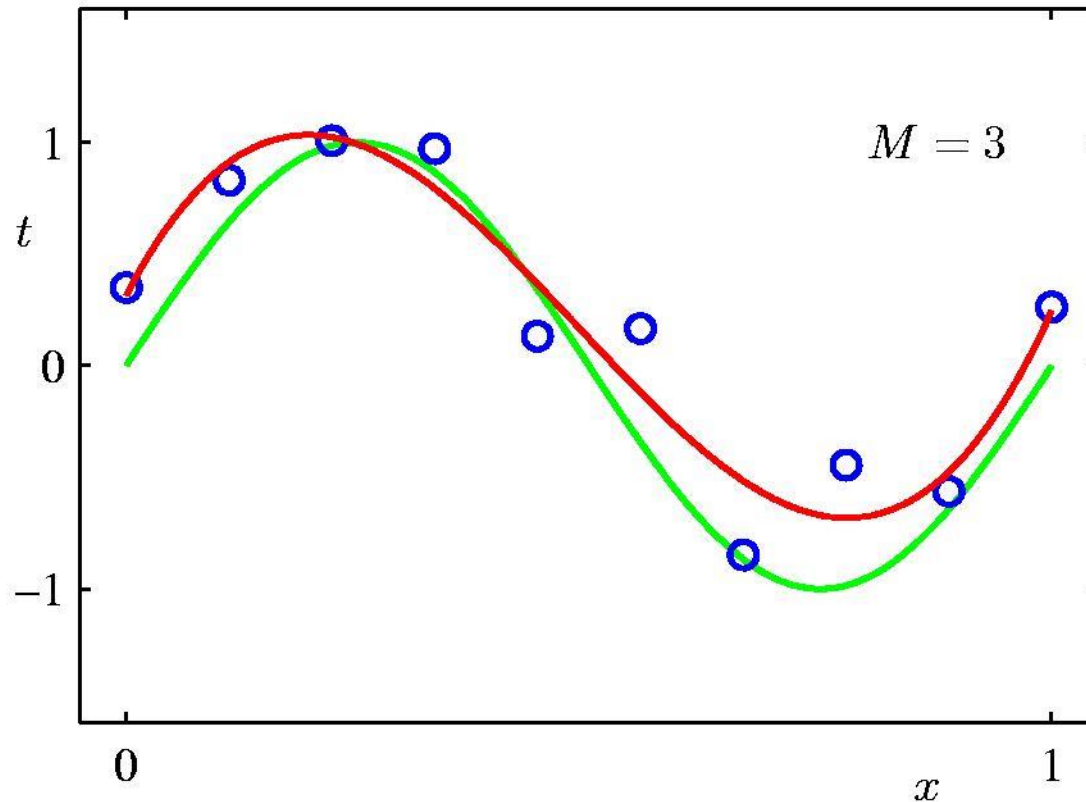
Toy example: 0th Order Polynomial



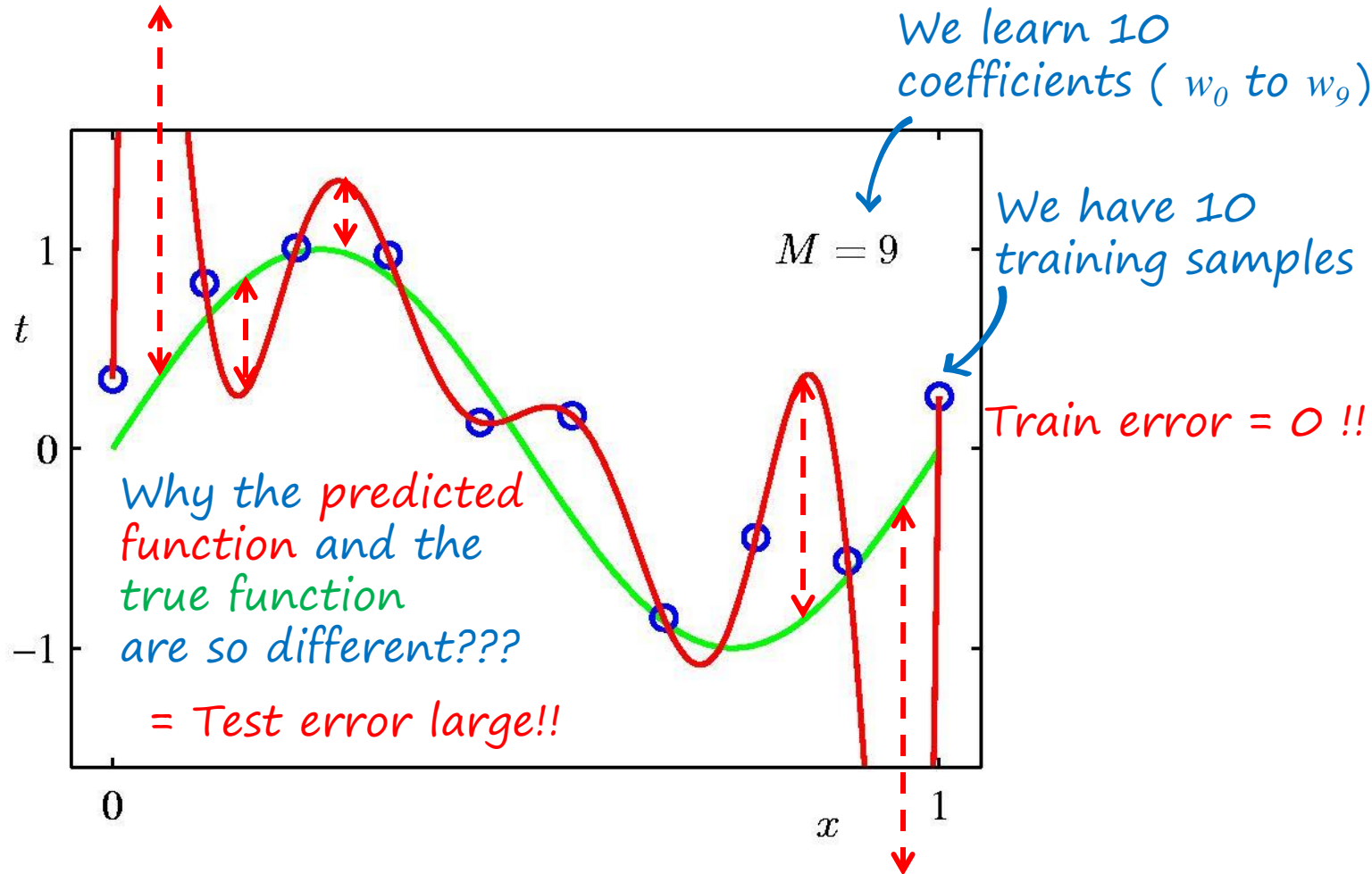
Toy example: 1st Order Polynomial



Toy example: 3rd Order Polynomial



Toy example: 9th Order Polynomial



Toy example: Polynomial Coefficients

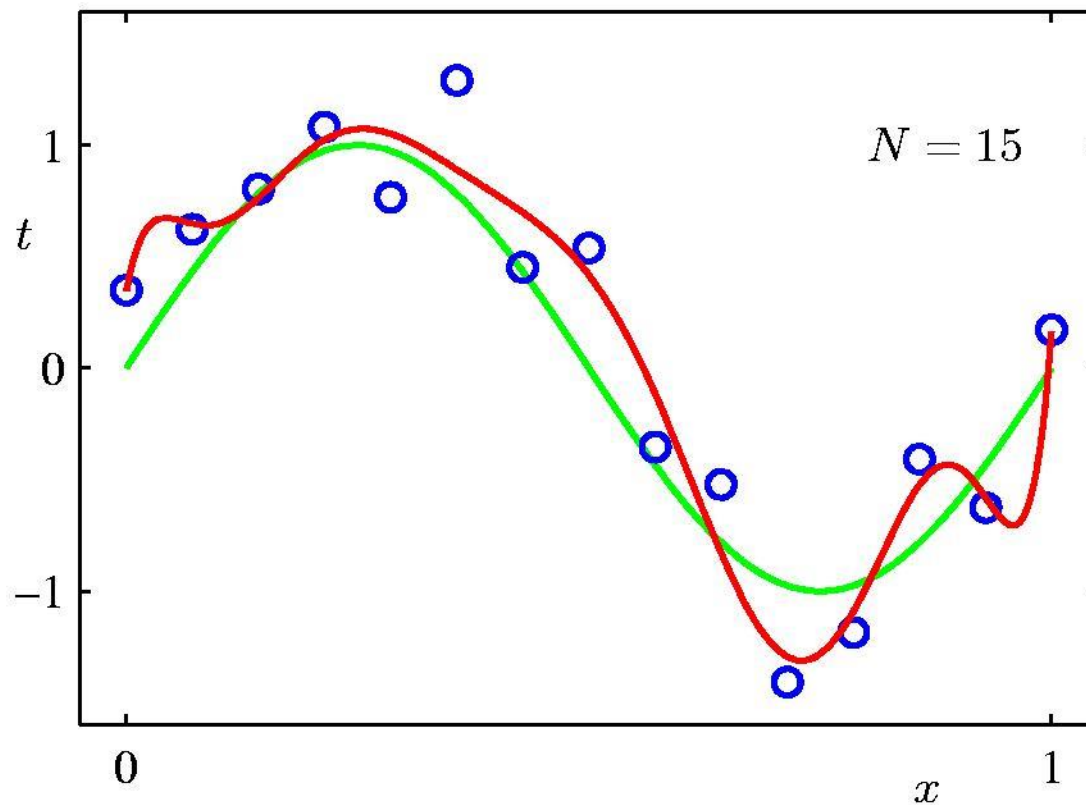
	$M = 0$	$M = 1$	$M = 3$	$M = 9$
w_0^*	0.19	0.82	0.31	0.35
w_1^*		-1.27	7.99	232.37
w_2^*			-25.43	-5321.83
w_3^*			17.37	48568.31
w_4^*				-231639.30
w_5^*				640042.26
w_6^*				-1061800.52
w_7^*				1042400.18
w_8^*				-557682.99
w_9^*				125201.43

Too high!!

Toy example: more data

9th Order Polynomial

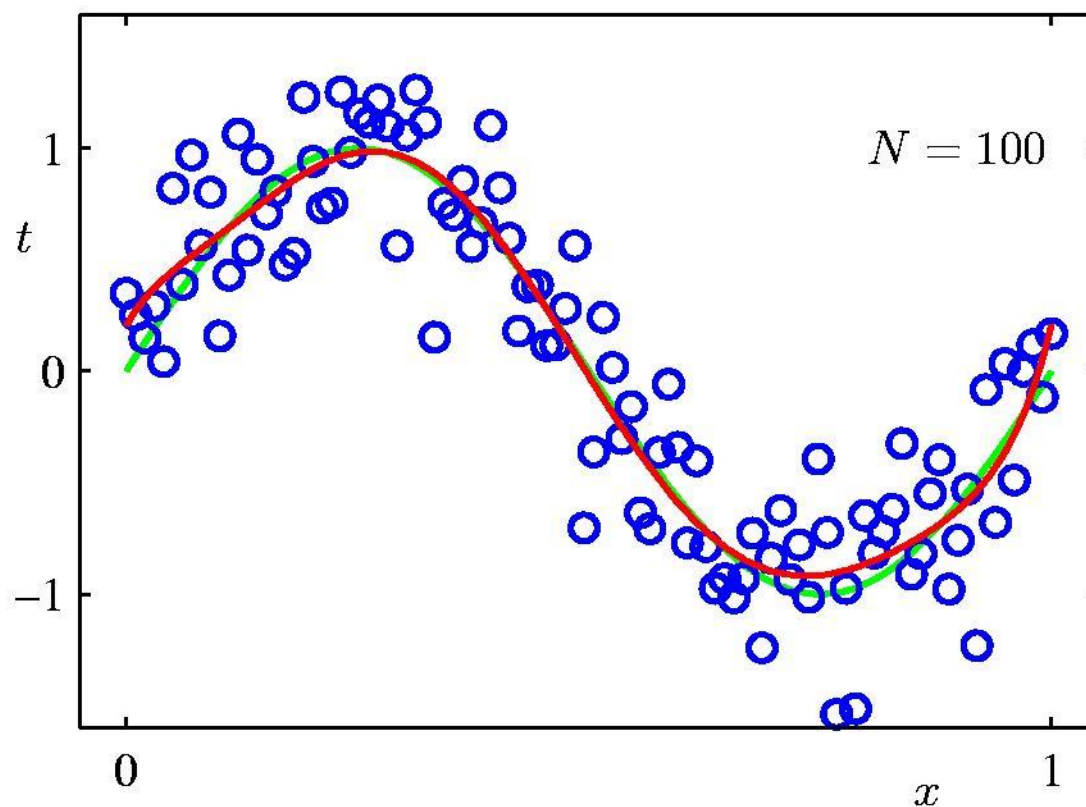
Train error > 0
Test error lower



Toy example: even more data

9th Order Polynomial

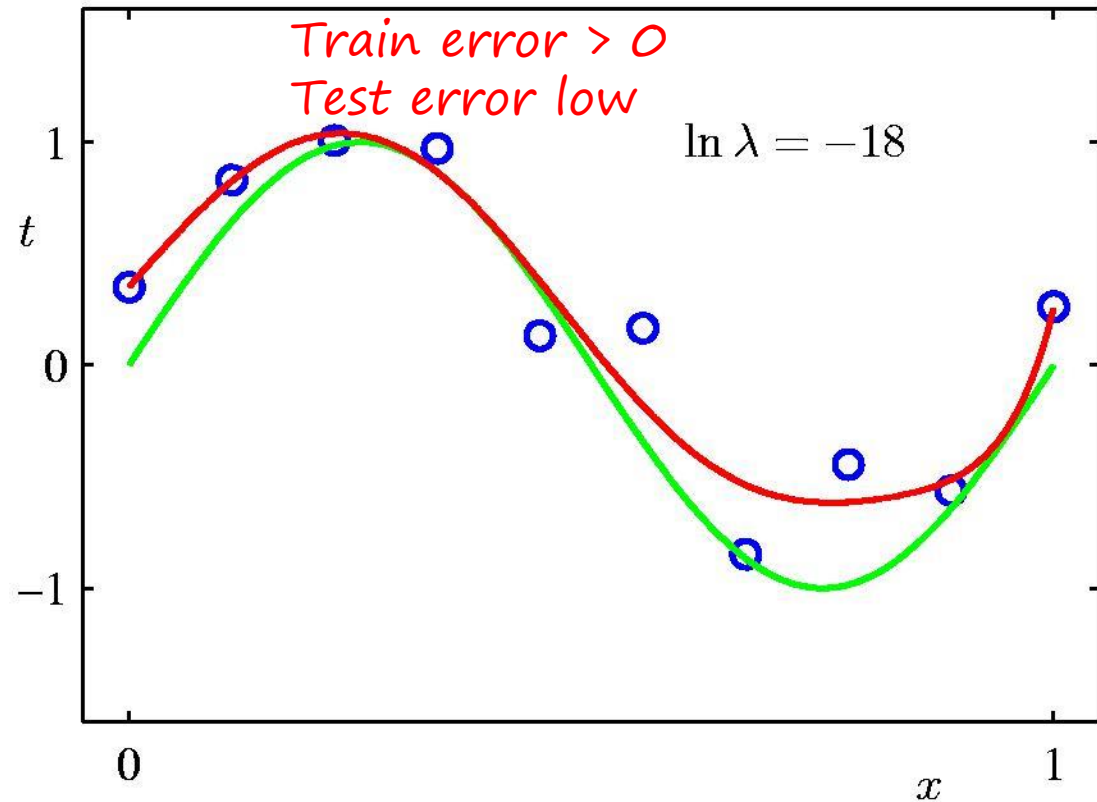
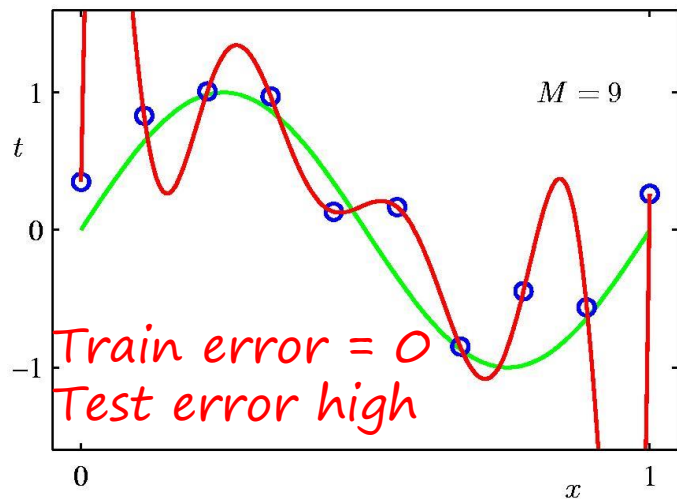
Train error \approx test error



Toy example: regularization

Penalize large coefficient values $\tilde{E}(\mathbf{w}) = \frac{1}{2} \sum_{n=1}^N \{y(x_n, \mathbf{w}) - t_n\}^2 + \frac{\lambda}{2} \|\mathbf{w}\|^2$

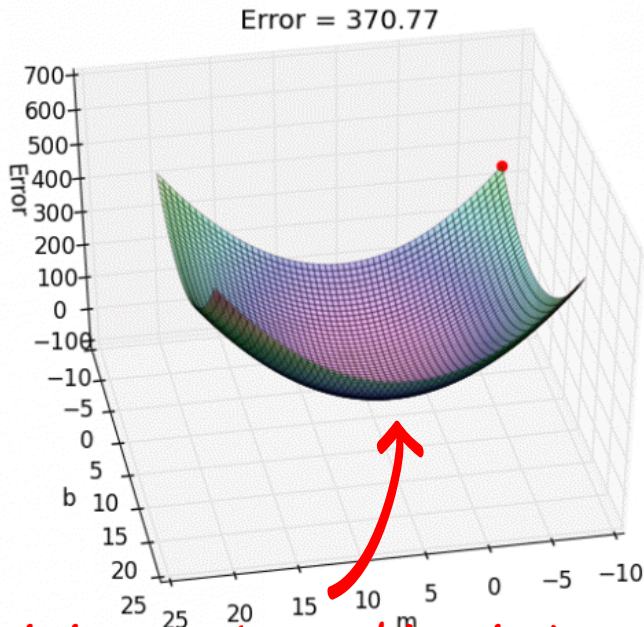
No penalty ($\lambda=0$)



Training: gradient descent

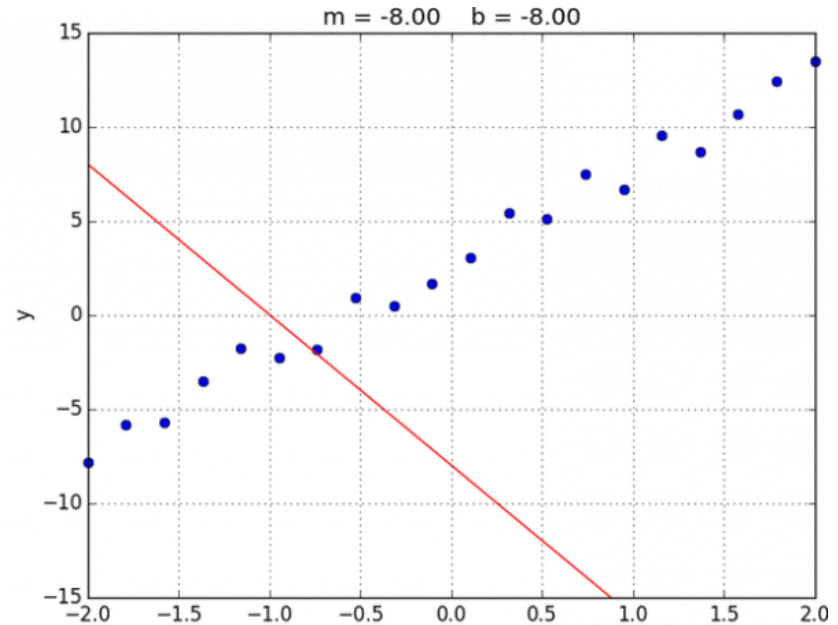
What if there is no analytical solution for the minimization?
Go step by step in the descending direction

Parameter space



Minimum (our objective)

Model $f(x) = mx + b$



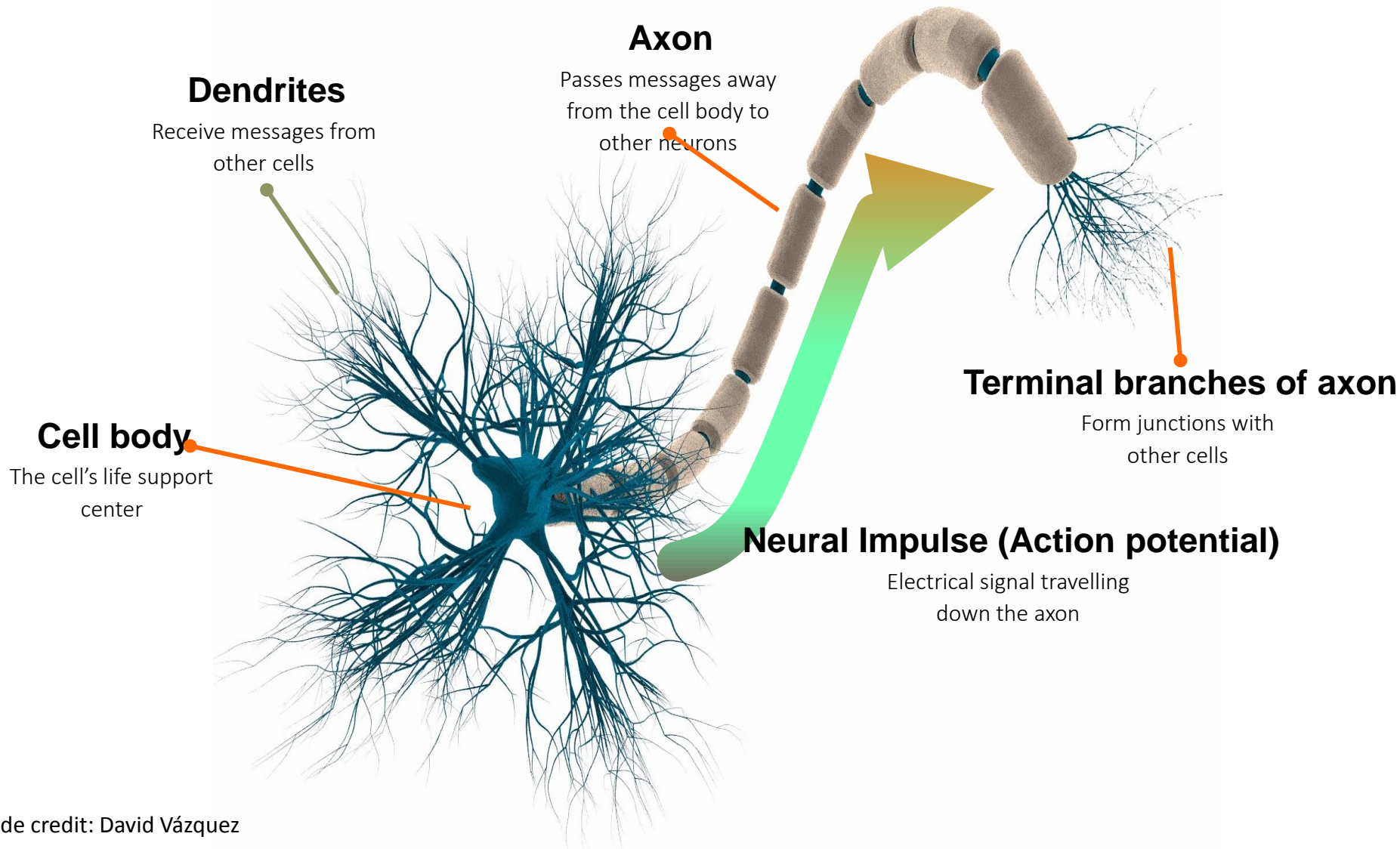
Update rule
 $m_{j+1} = m_j - \gamma \frac{\partial E}{\partial m_j}$
 $b_{j+1} = b_j - \gamma \frac{\partial E}{\partial b_j}$
(γ =learning rate)

Today's plan

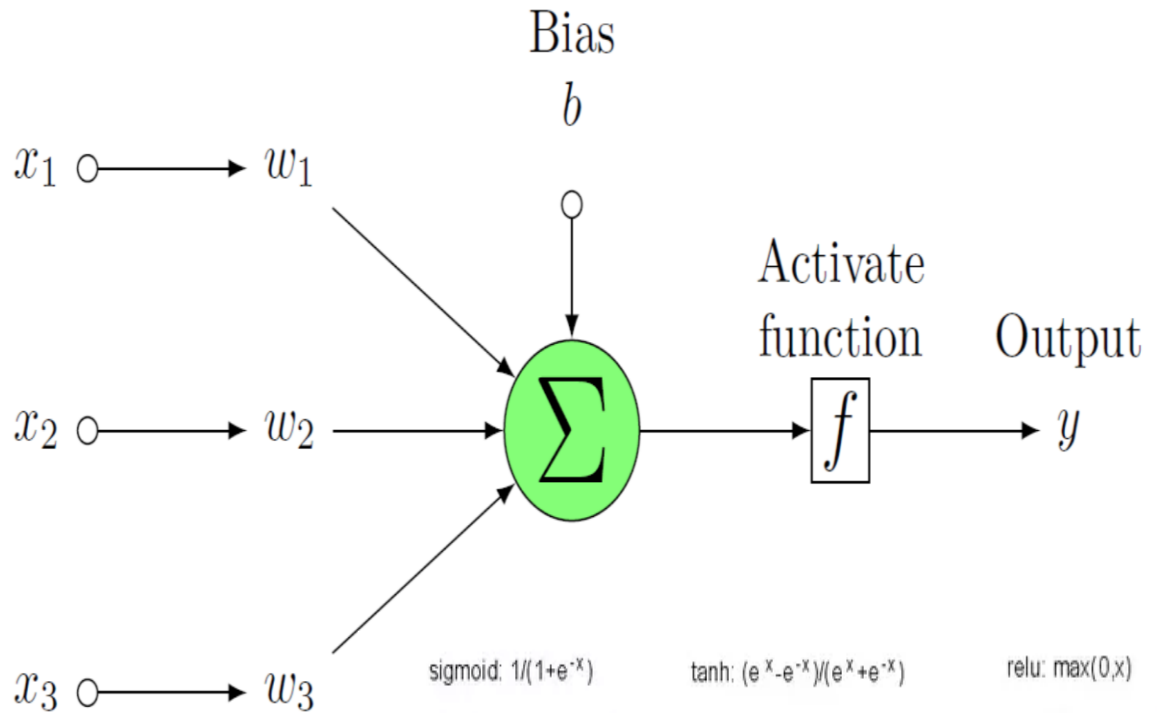
- Machine learning
- Neural networks
 - Artificial neural networks
 - Convolutional neural networks
 - Recurrent neural networks
 - Deep learning
- Deep learning in computer vision
- Fun stuff

Biological neuron

A cell that processes and transmits information through electrical and chemical signals (i.e. synapses)



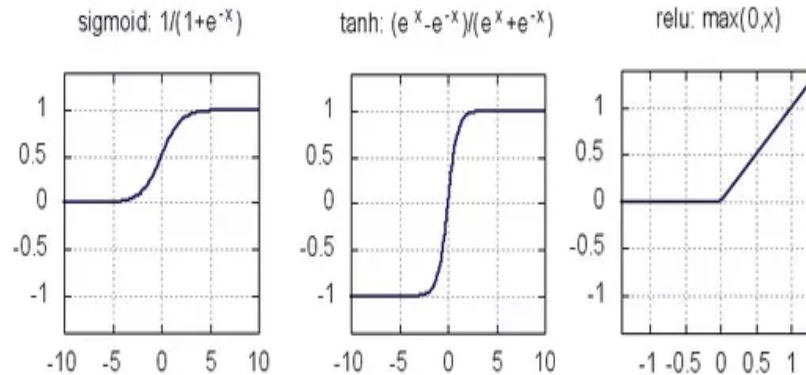
Artificial neuron



Neuron pre-activation (or input activation): $a(x) = \sum_{i=0}^n (w_i x_i) + b = W^T x + b$

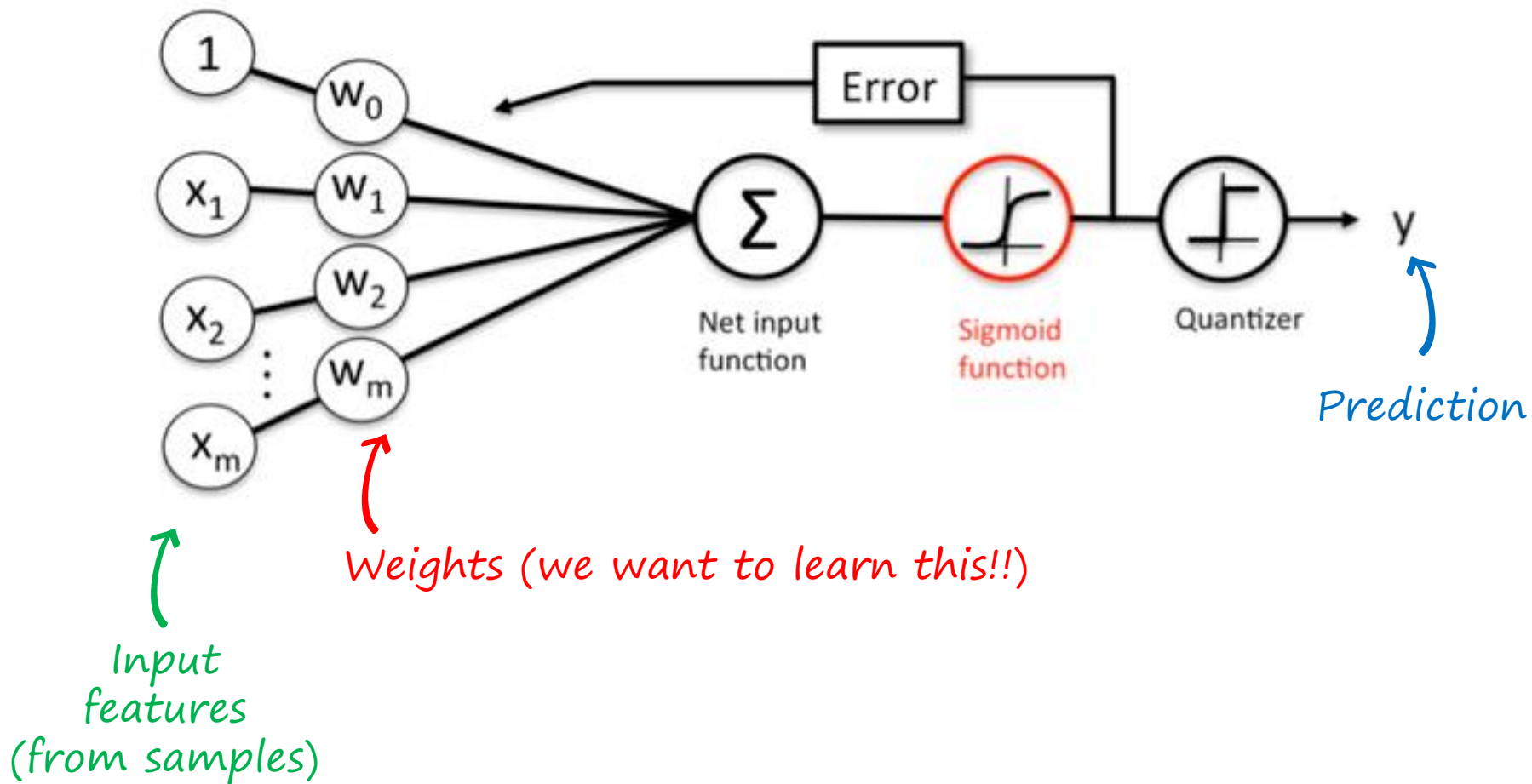
Neuron output
 $y = f(a(x)) = f(W^T x + b)$

The activation function (f) is a non-linear function. For instance Sigmoid, Tanh or ReLU

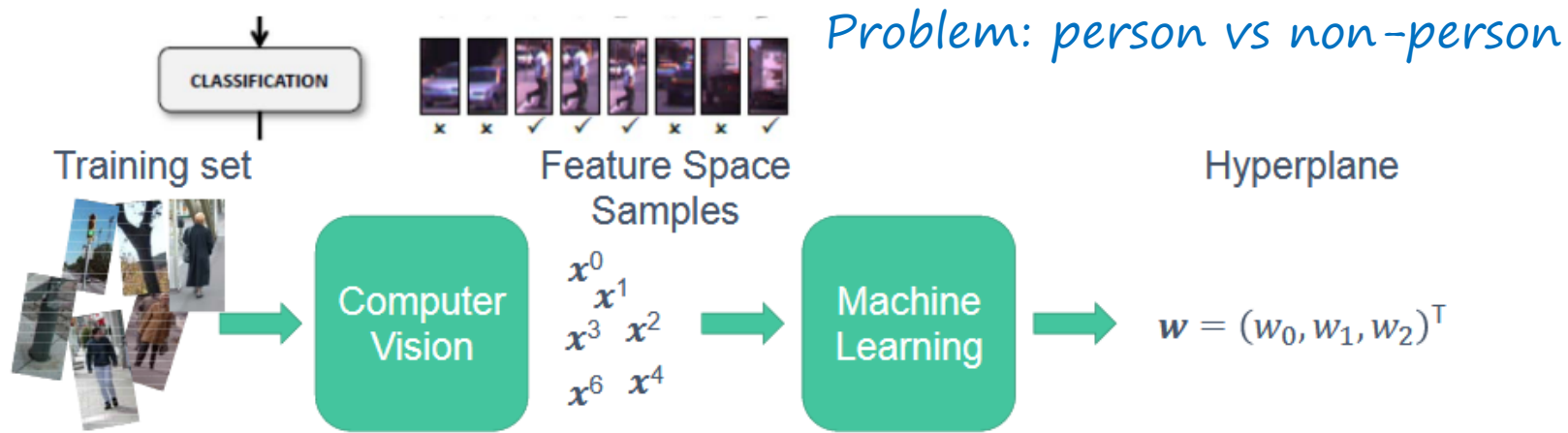


Human brain vs artificial neural network
Human brain: ~100-1000 trillion synapses
Artificial neural network: ~1-10 billion synapses

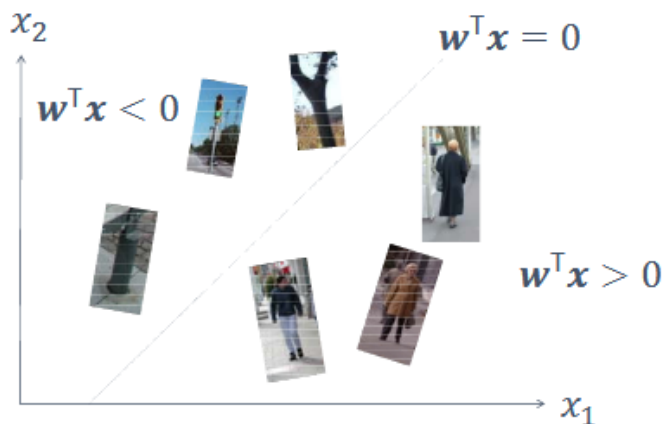
One layer: logistic regression



One layer: linear classifier (binary)



- Linear binary classifier in a feature space of $n=2$ dimensions.



Only can learn linear separation

$$\mathbf{w} = (w_0, w_1, w_2)^T$$

$$\mathbf{x} = (1, x_1, x_2)^T$$

$$\text{Classify}(\mathbf{x}; \mathbf{w}, T) = \text{Threshold}(\mathbf{w}^T \mathbf{x}, T)$$

$$\text{Threshold}(y, T) = \begin{cases} 0 & \text{si } y < T \\ 1 & \text{si } y > T \\ ? & \text{si } y = T \quad (\text{design decision}) \end{cases}$$

Demo: MNIST dataset

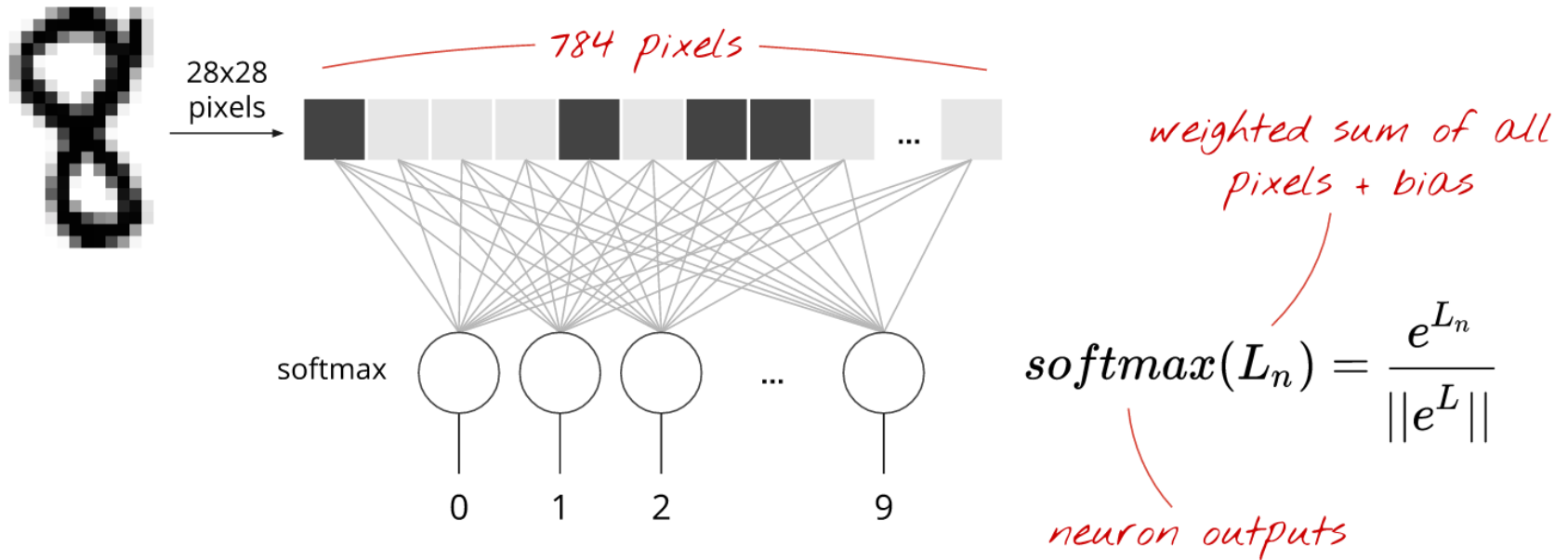


10 classes (0,1,2,3,4,5,6,7,8,9)

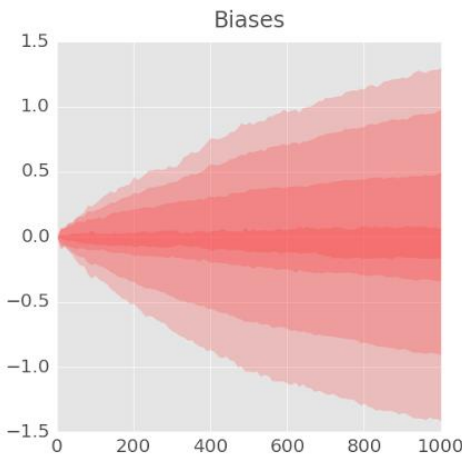
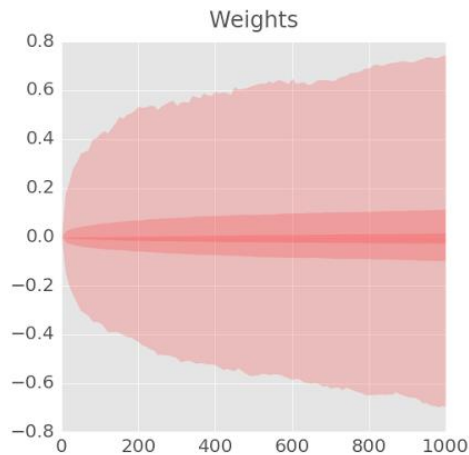
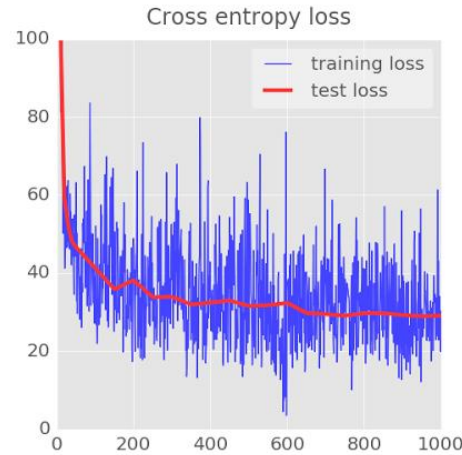
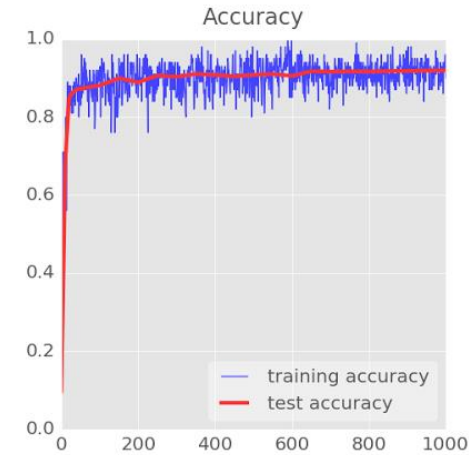
60000 images for training, 10000 for test

28x28 grayscale images (=784 values)

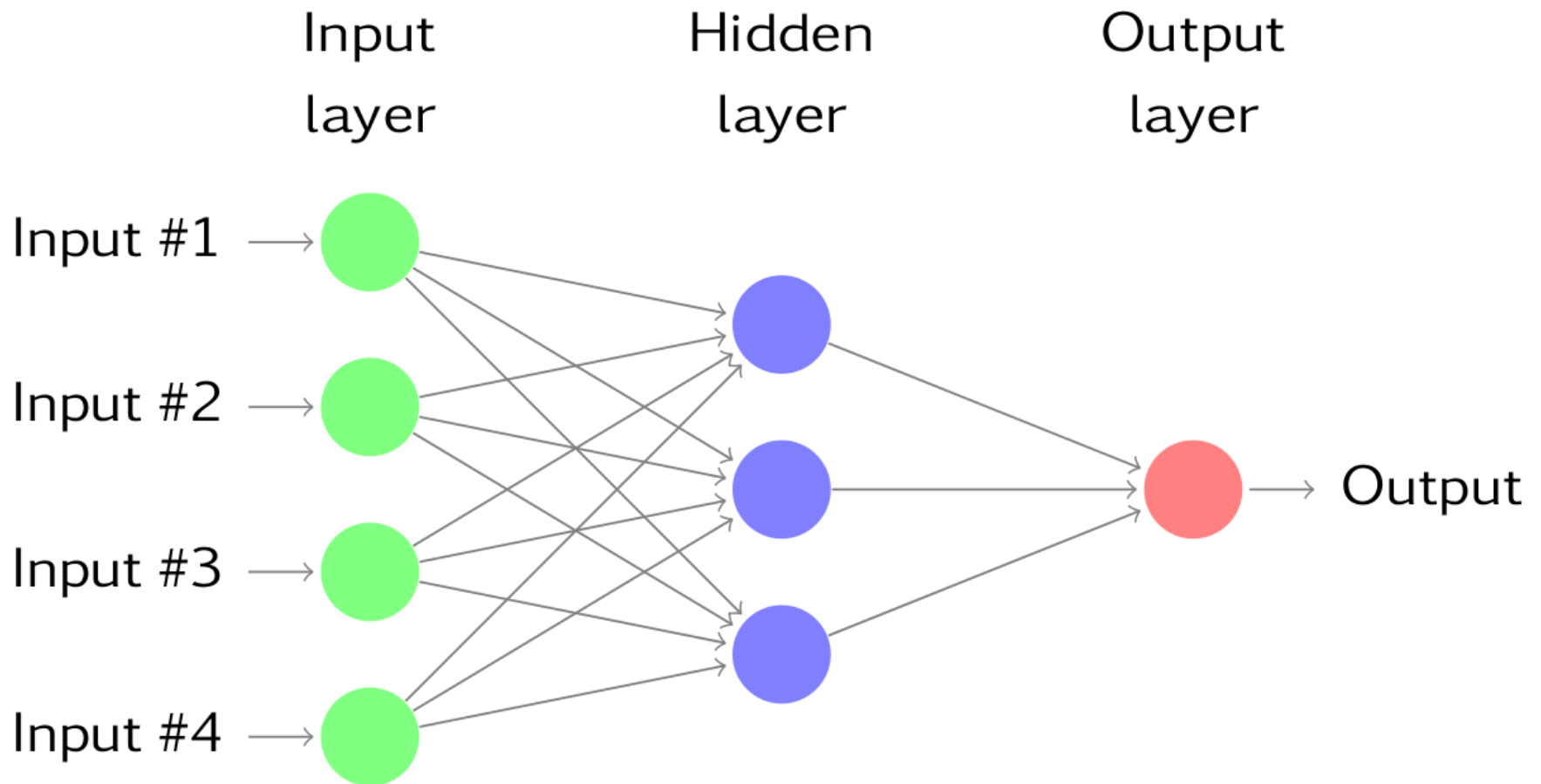
Demo: logistic regression (1 layer NN)



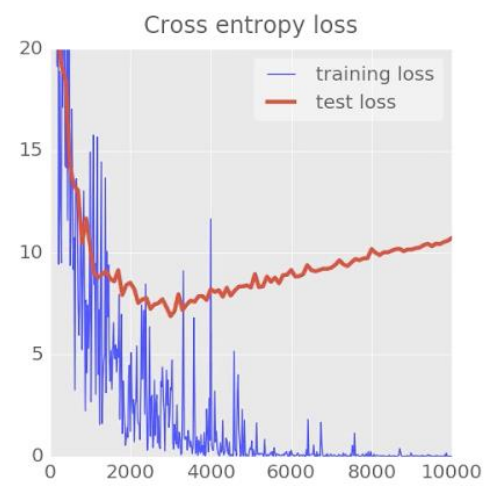
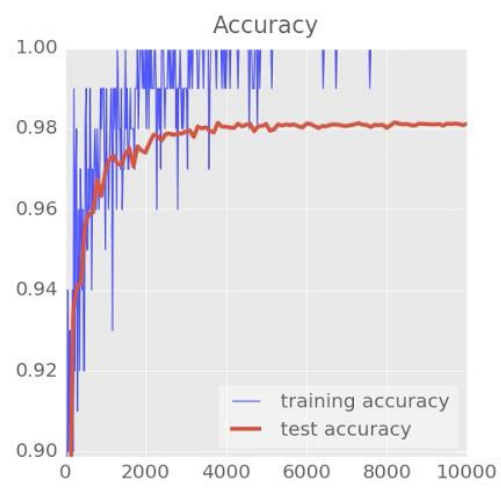
Demo: logistic regression (1 layer NN)



Two layers



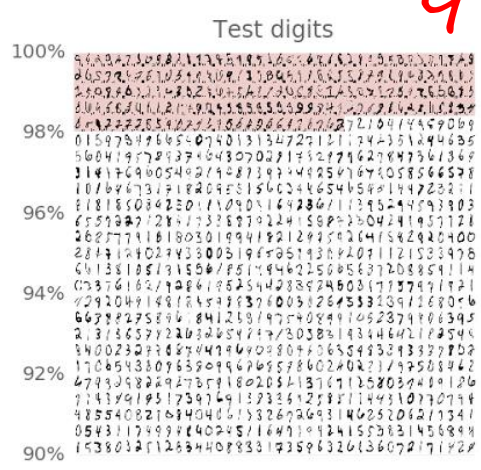
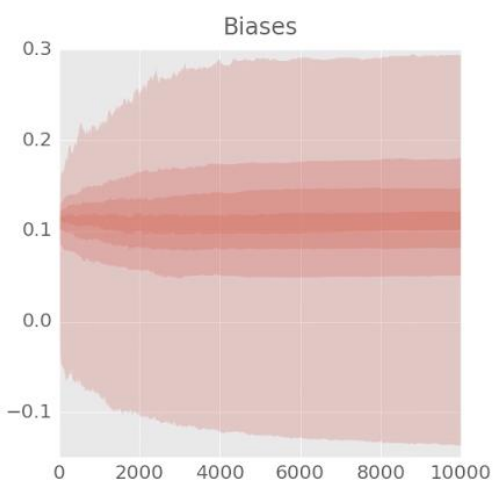
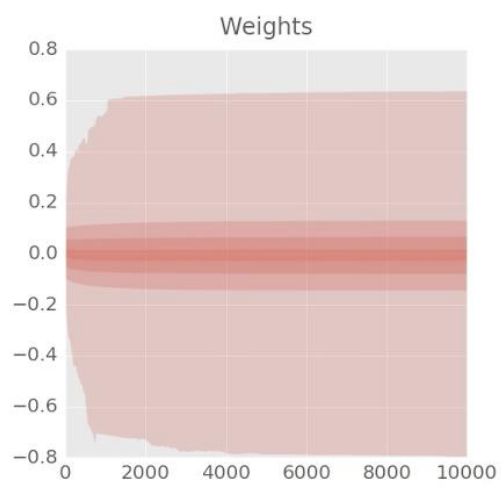
Demo: multilayer network



Training digits

```
5002467039
4017569606
0610060639
8174636959
0516327573
4708155271
6442136734
0780701174
3370380189
4479508161
```

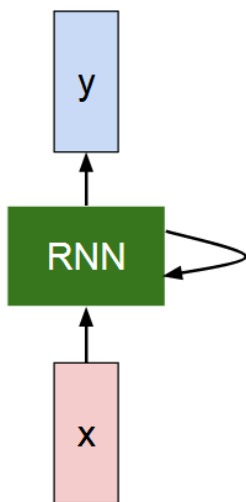
98%



Recurrent neural networks (RNNs)

(Vanilla) Recurrent Neural Network

The state consists of a single "hidden" vector h :



$$h_t = f_W(h_{t-1}, x_t)$$

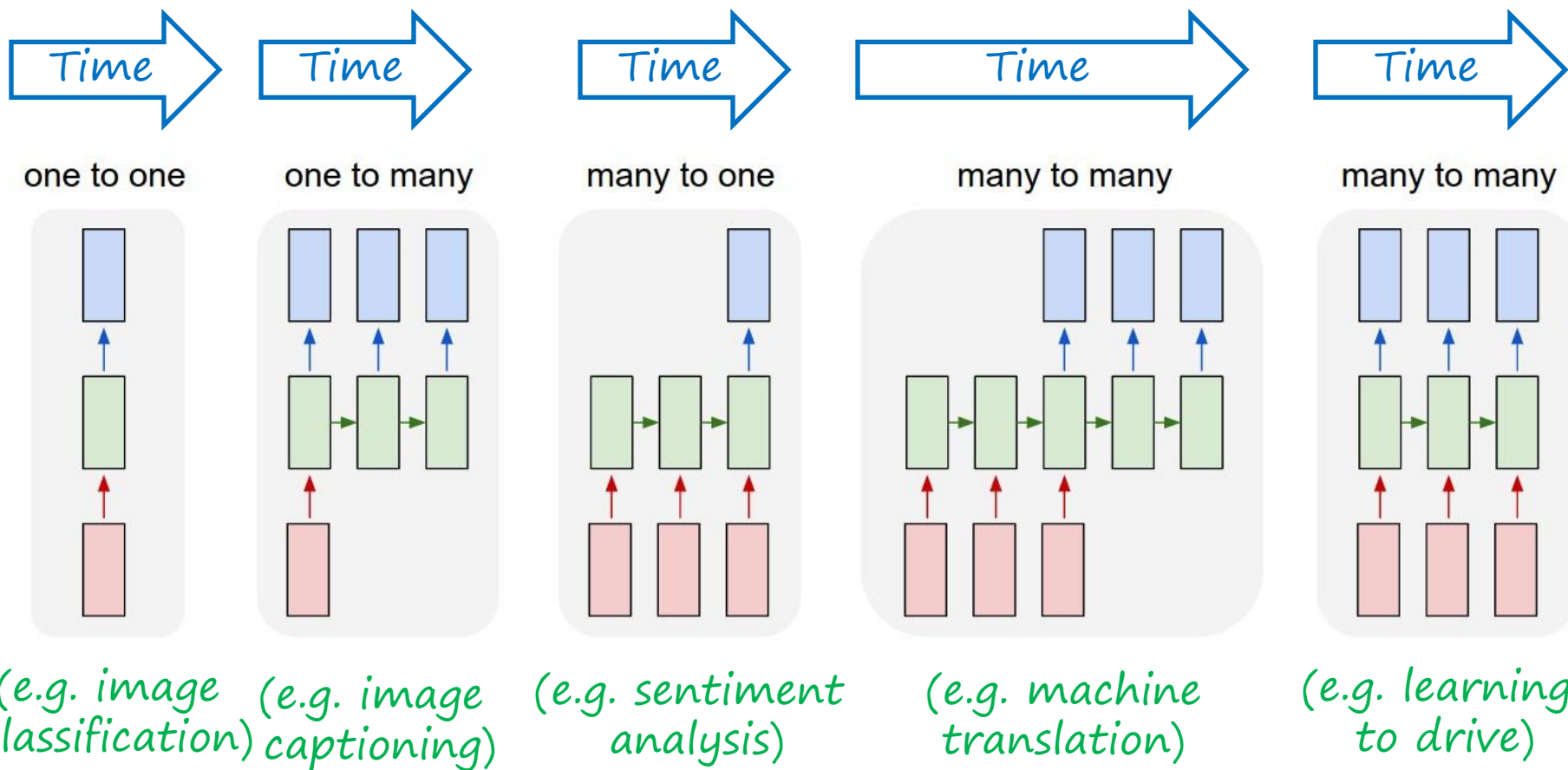


$$h_t = \tanh(W_{hh}h_{t-1} + W_{xh}x_t)$$

$$y_t = W_{hy}h_t$$

Use Long Short-term Memory (LSTM) units (nobody uses this simple vanilla RNNs in practice)

Unrolling RNNs



Adapted from: A. Karpathy

<http://karpathy.github.io/2015/05/21/rnn-effectiveness>

Demo: recurrent neural networks

Guess the letter!

See how well you can figure out what comes next. It's always a letter of the English alphabet (case insensitive) or a space, a comma, an apostrophe, or a period. That's 30 possibilities for every character. Just start typing! The correct text appears here:

Th

What you enter will appear here:

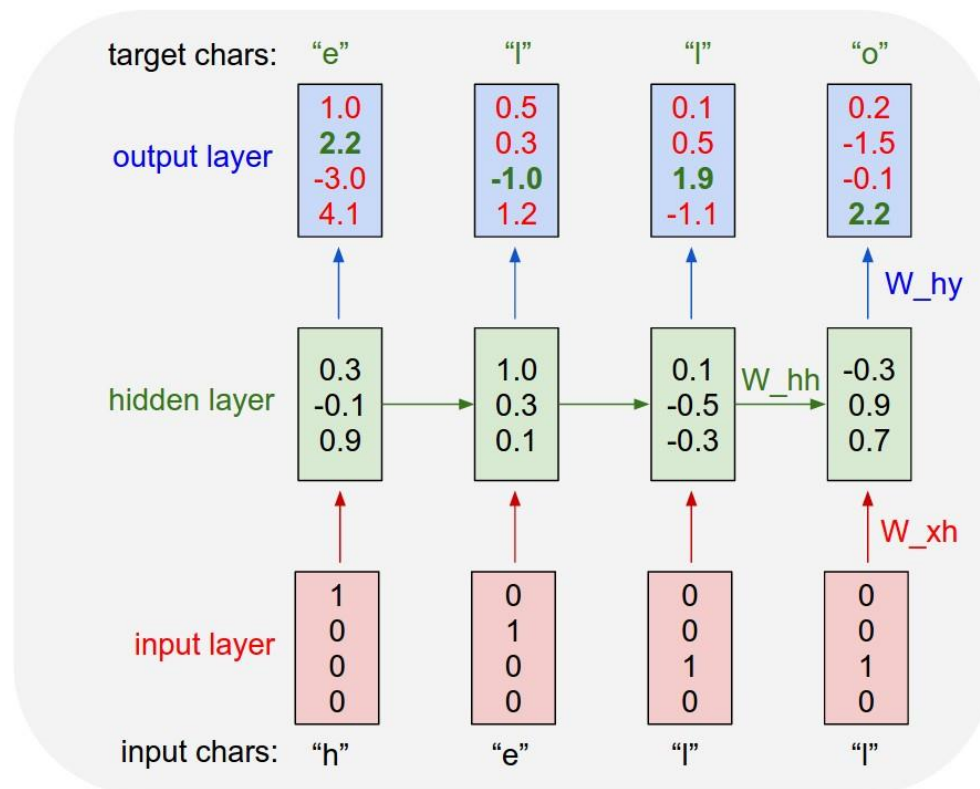
Th

[incomplete] accuracy: [unknown]; perplexity: [unknown]

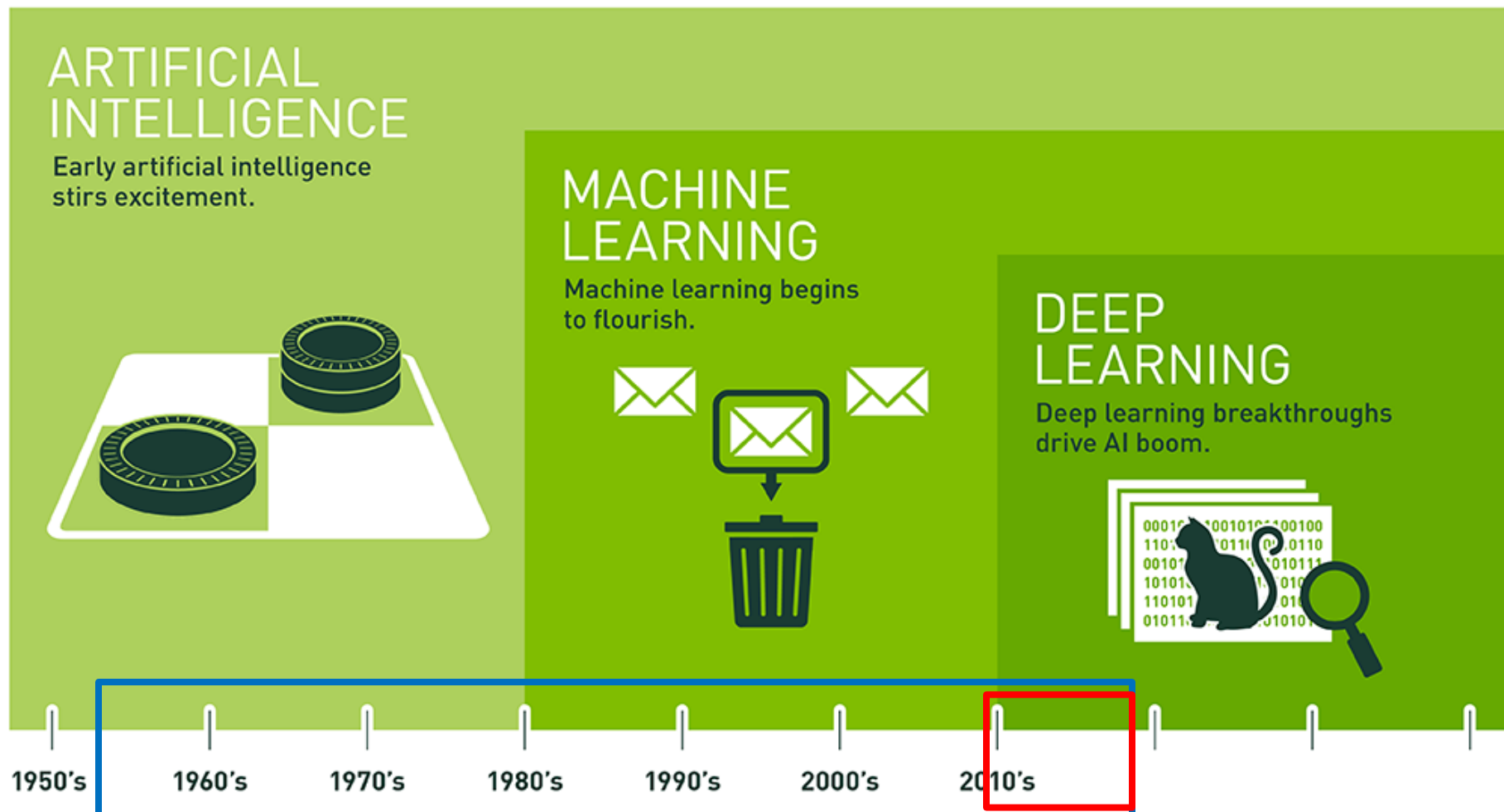
(0 of 29 characters; 0 correct) (This is passage 1 of 20.)

No keyboard? Select here: (Then zoom out.)

Demo: recurrent neural networks



What is deep learning?



Artificial neural networks = Deep learning

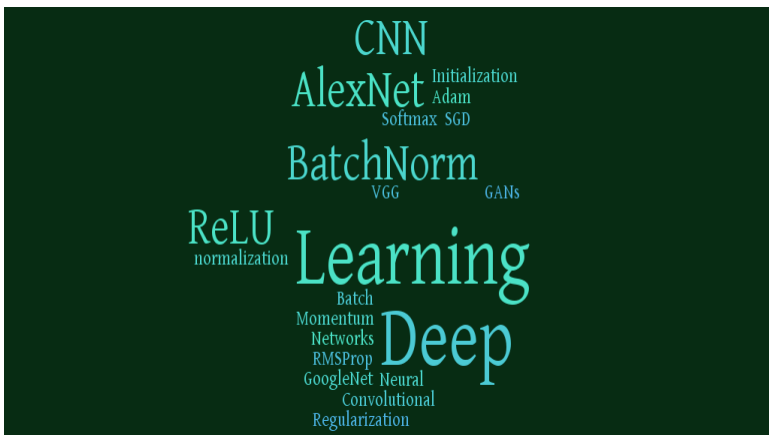
Why does it work now?



Large amount of (annotated) data



Large amount of computing resources (GPUs)



Better understanding of training algorithms

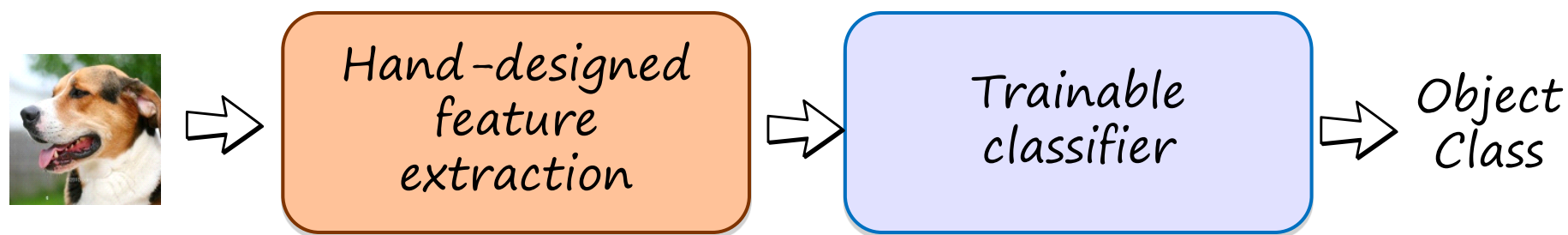


Large community of researchers and open source implementations

Today's plan

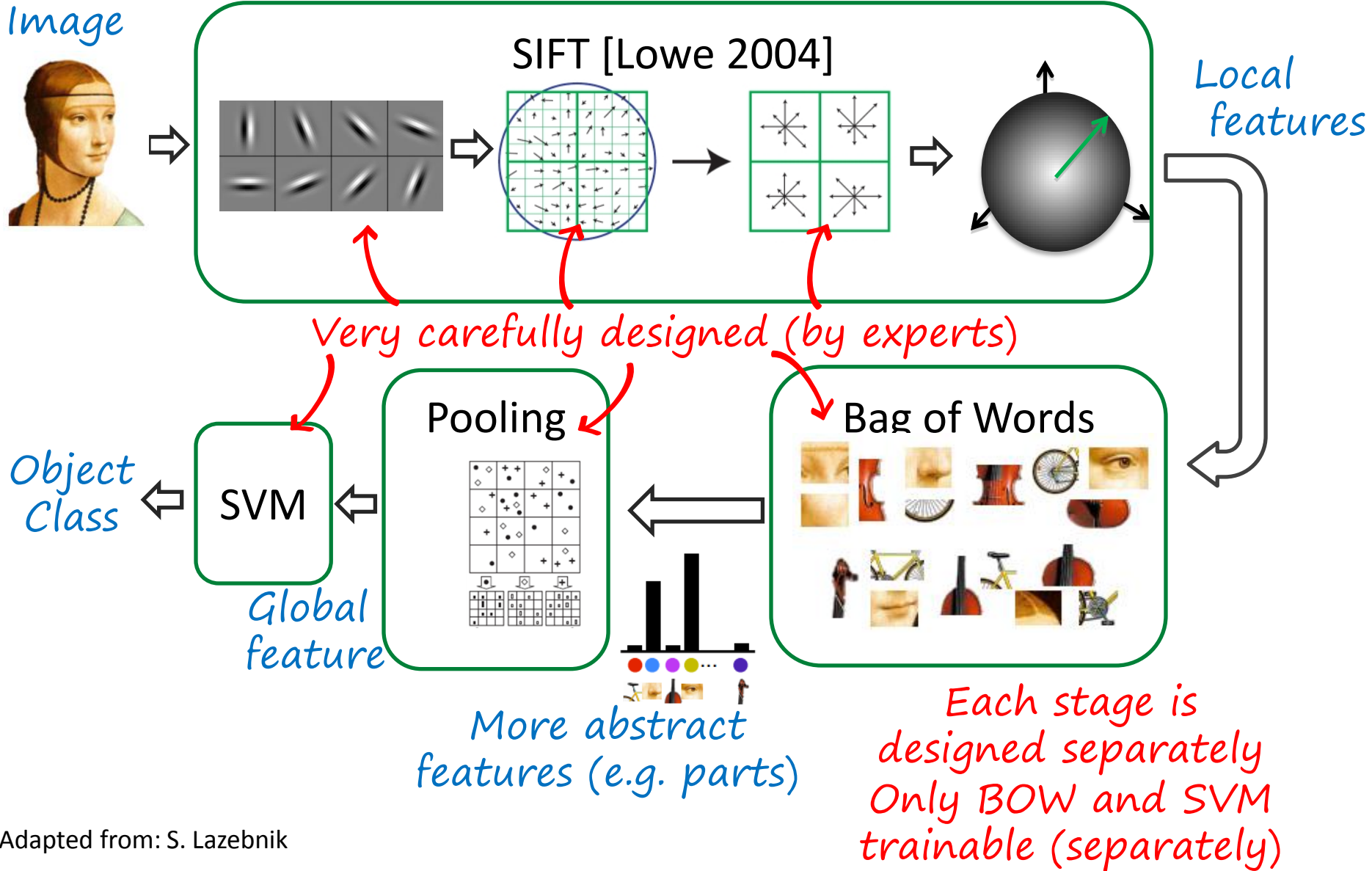
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Traditional Recognition Approach



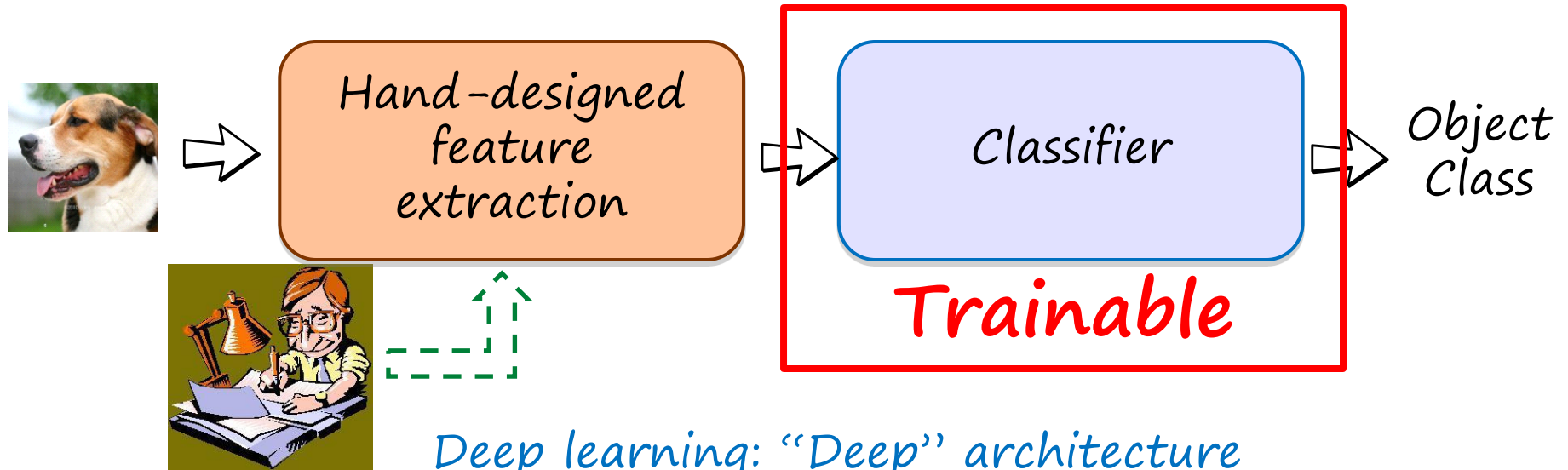
- *Features are not learned*
- *Trainable classifier is often generic (e.g. SVM)*

Traditional approach to visual recognition

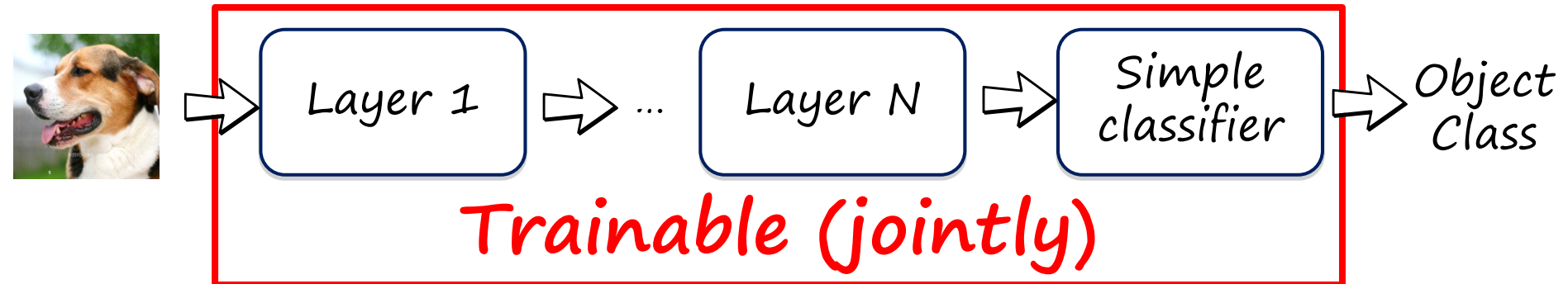


“Shallow” vs. “deep” architectures

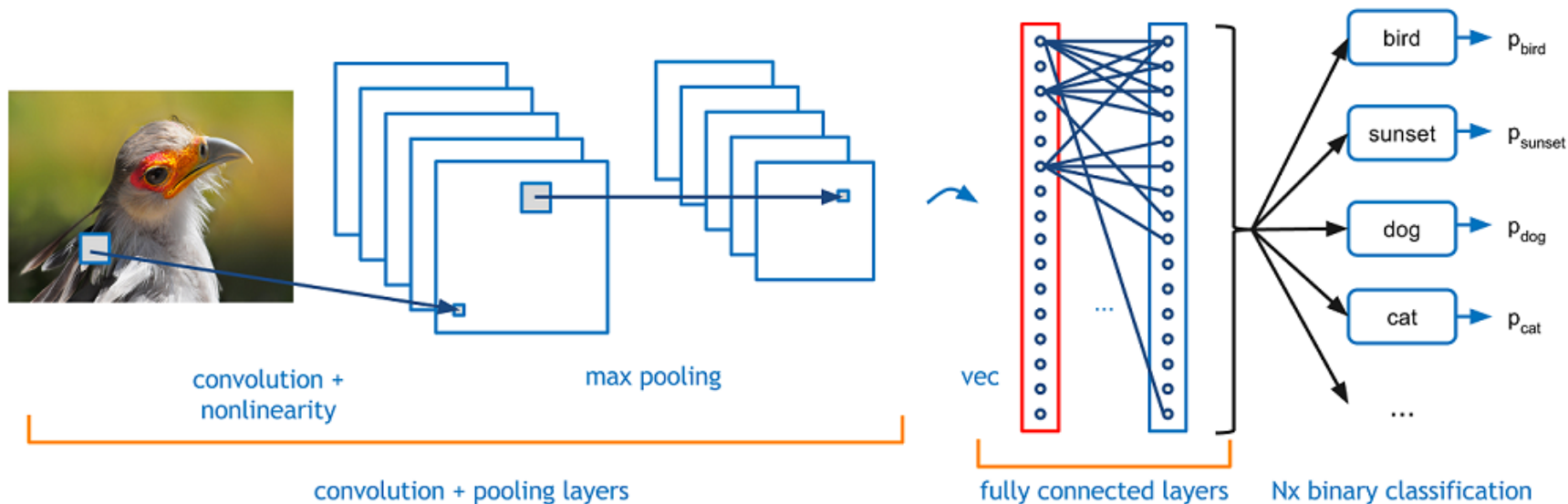
Traditional recognition: “Shallow” architecture



Deep learning: “Deep” architecture



Convolutional neural networks (CNNs)



*Inspired by the visual system
Old idea (Fukushima 1980, LeCun 1986)
Worked well in character recognition
Larger networks didn't work*

Filters as linear convolutions

- Dependencies are local
- Translation invariance
- Few parameters (filter weights)
- Stride can be greater than 1 (faster, less memory)

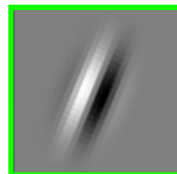
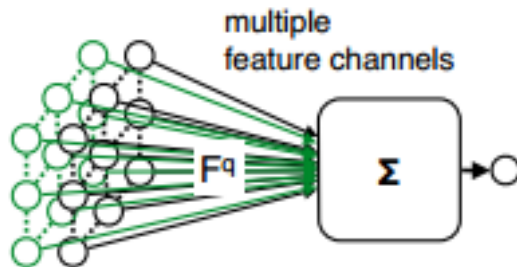
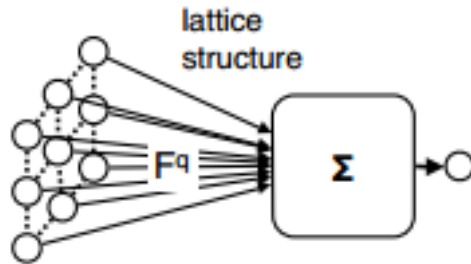
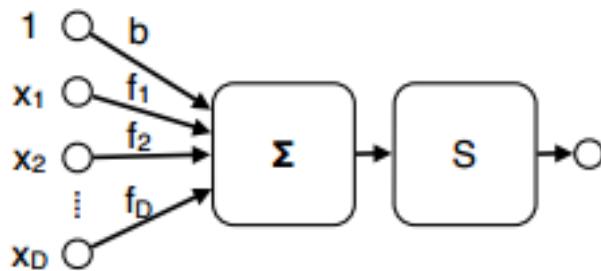


Input

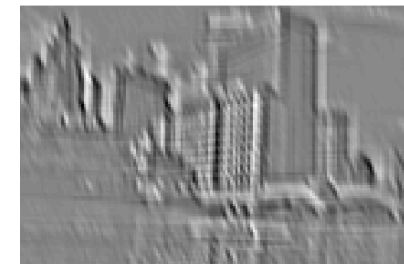
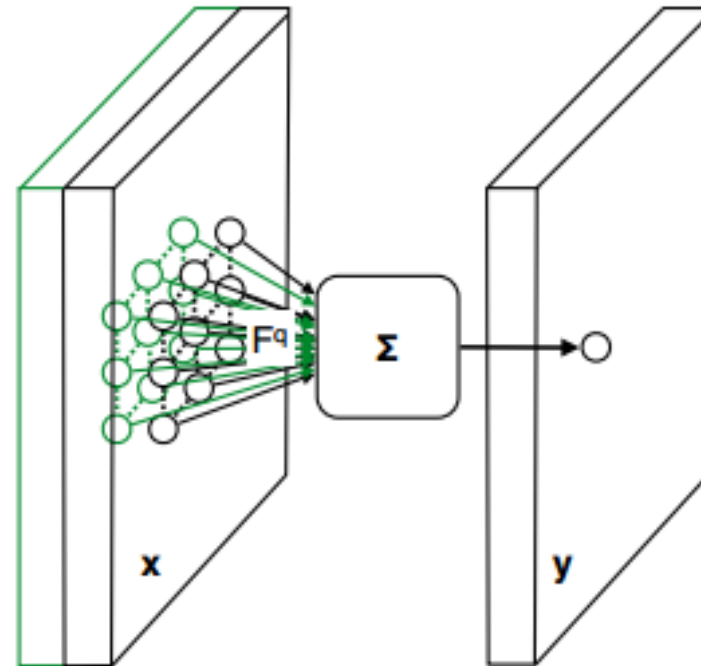


Feature Map

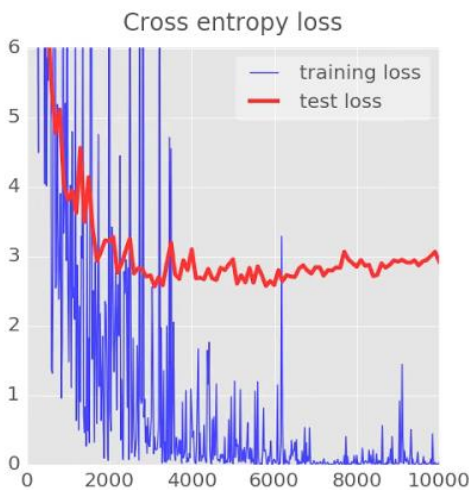
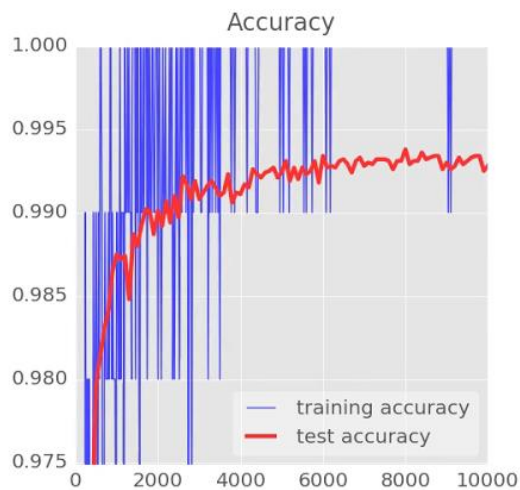
Linear convolution as a neural network



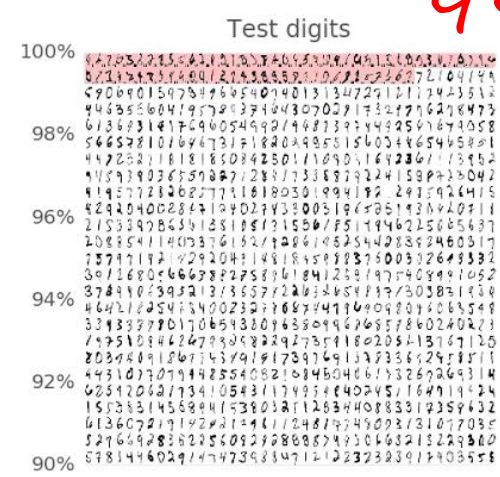
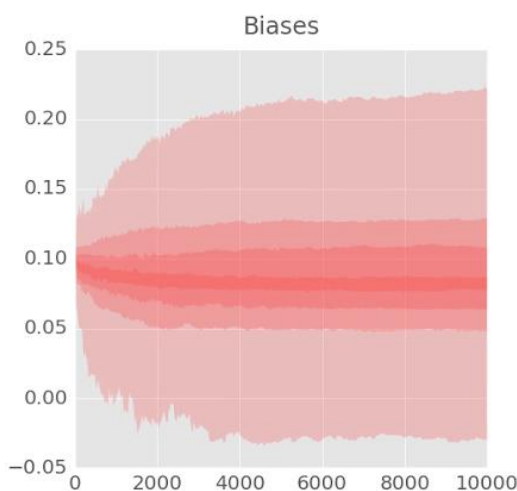
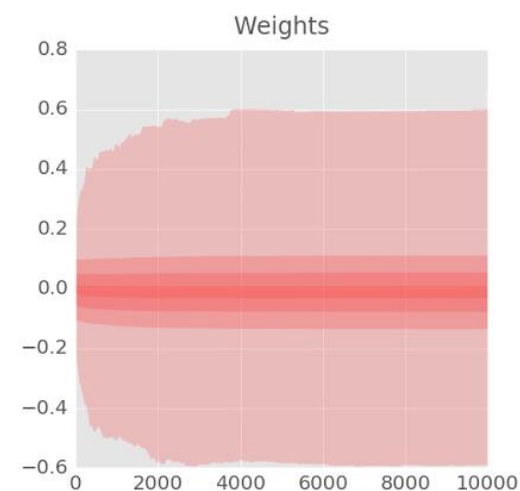
local and translation invariant action



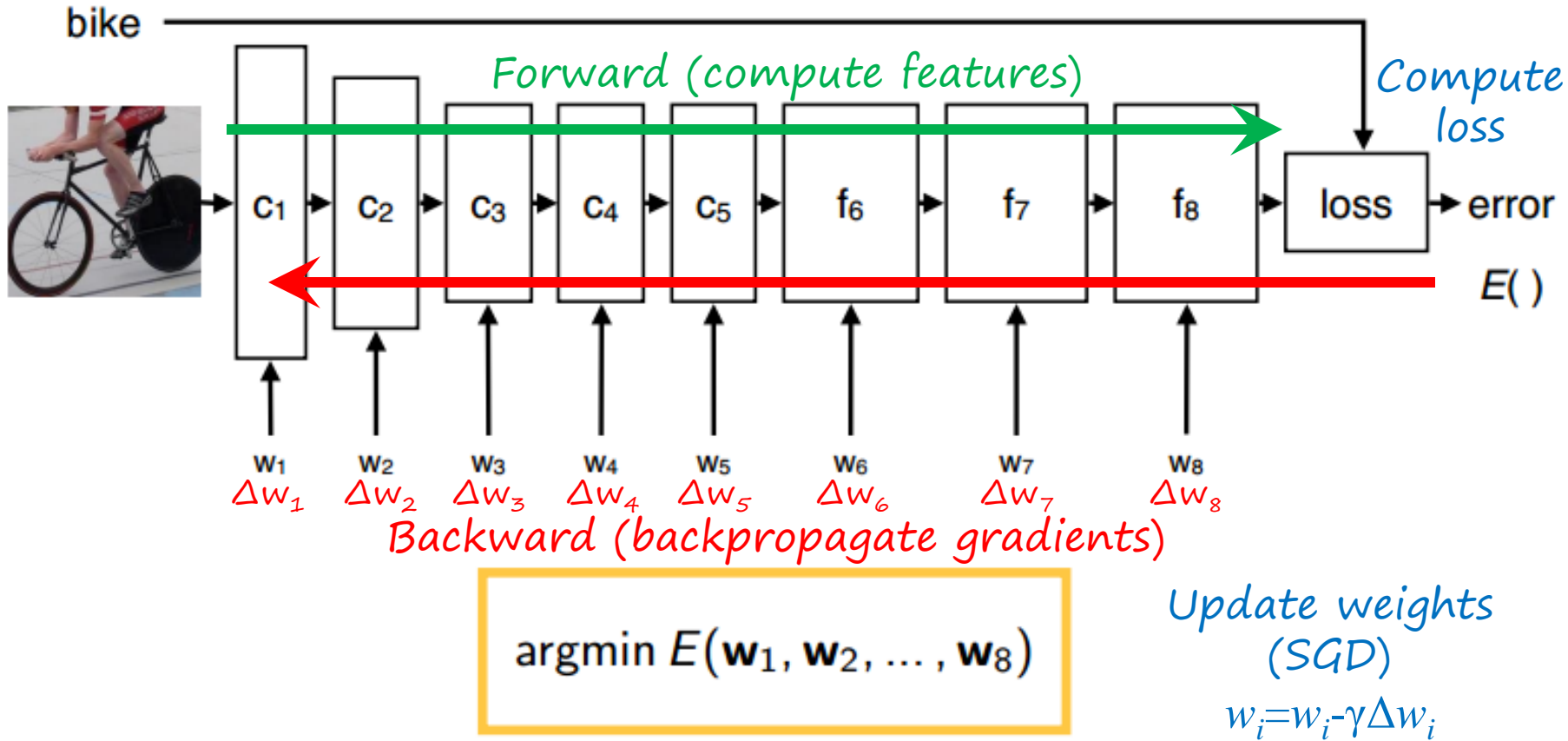
Demo: convolutional network



99.3%



Training a CNN



Stochastic gradient descent
(with momentum, dropout, ...)

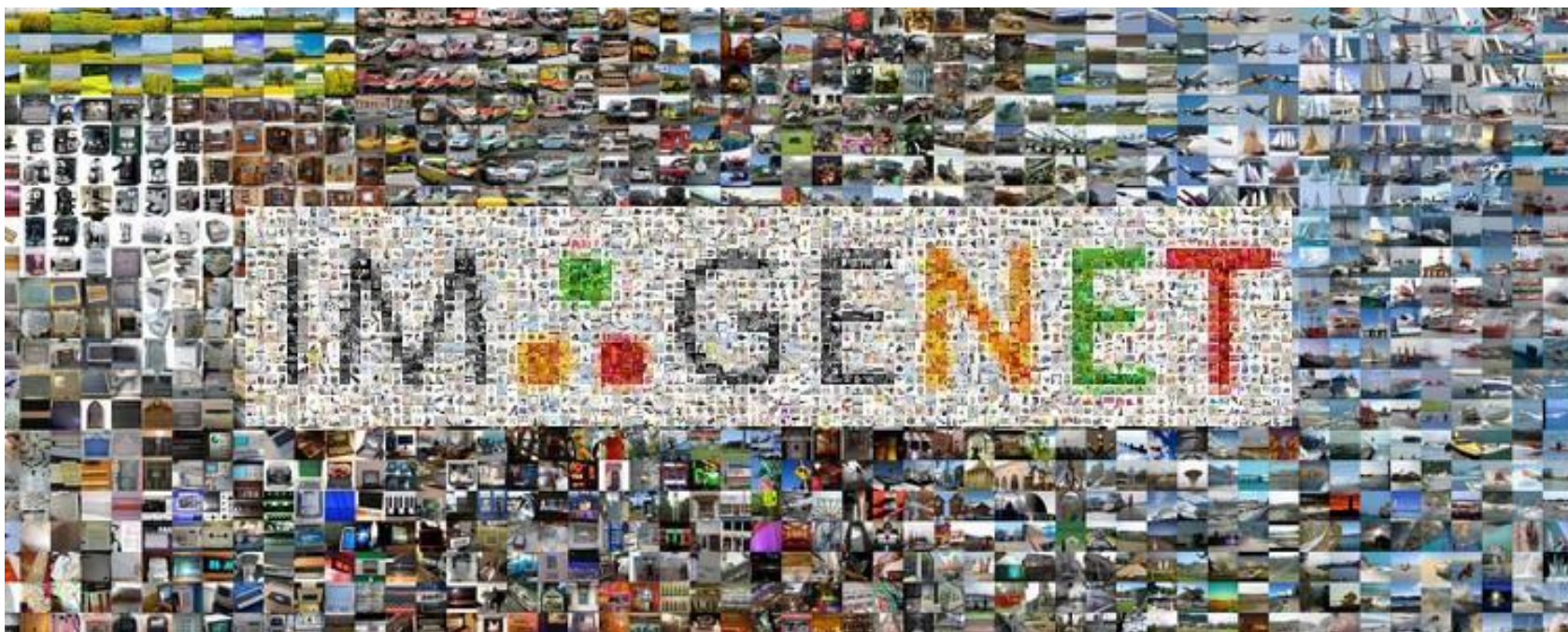
The revolution: ImageNet

Large visual database

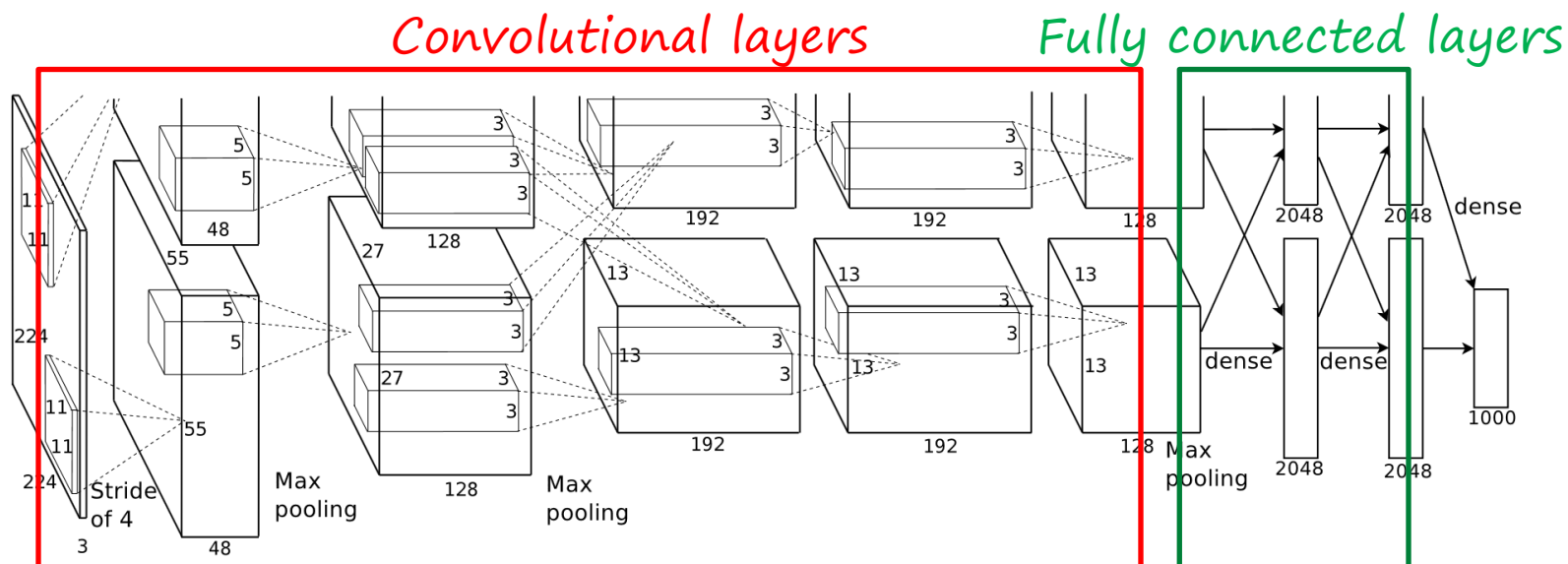
- Over 10 million images
- Manually annotated
- Follows WordNet concept structure

ILSVRC2012

- Subset with 1000 classes
- 1.2 million images
- Used in competitions
- Used to train most of the networks



The revolution: AlexNet



- Khrizevsky et al winning ImageNet 2012. AlexNet:
 - 7-layers NN (5 conv layers+2 fully connected)
 - 650k neurons
 - 60 million parameters (630 million connections)
 - Trained on two GPUs for about a week

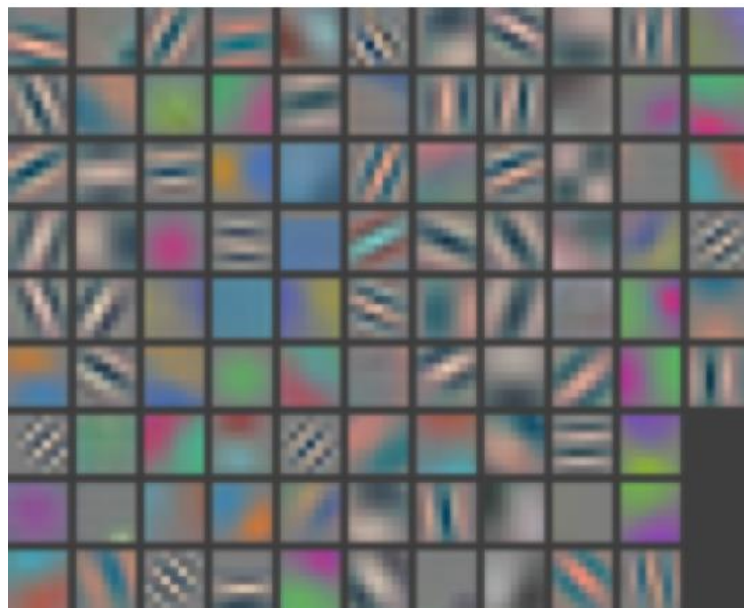
AlexNet in ImageNet ILSVRC 2012

Method	Classification (top 5 error, 1000 categories)	Classification and localization
Supervision (AlexNet CNN)	16.4%	34.1%
University of Tokyo	26.1%	53.6%
Oxford University Computer Vision Group	26.9%	50.0%
INRIA	27.0%	-
University of Amsterdam	29.5%	-

Shallow models

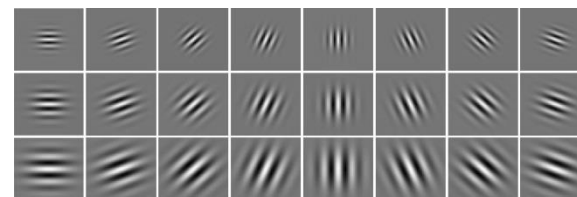
Understanding AlexNet: layer 1

Learned from data!

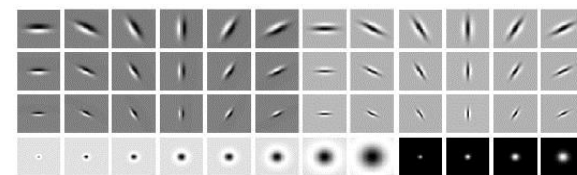


*Layer 1 filters
(convolutional)
This looks familiar*

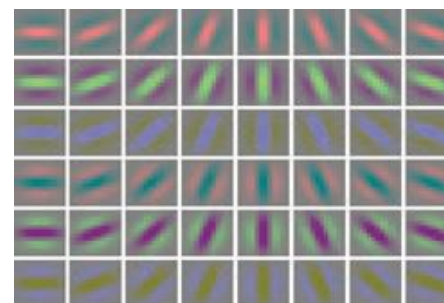
Handcrafted



Gabor filters



LM filters



*Color
versions*

Understanding AlexNet: layer 5

Visualize sample images that excite a given neuron the most

Layer 5

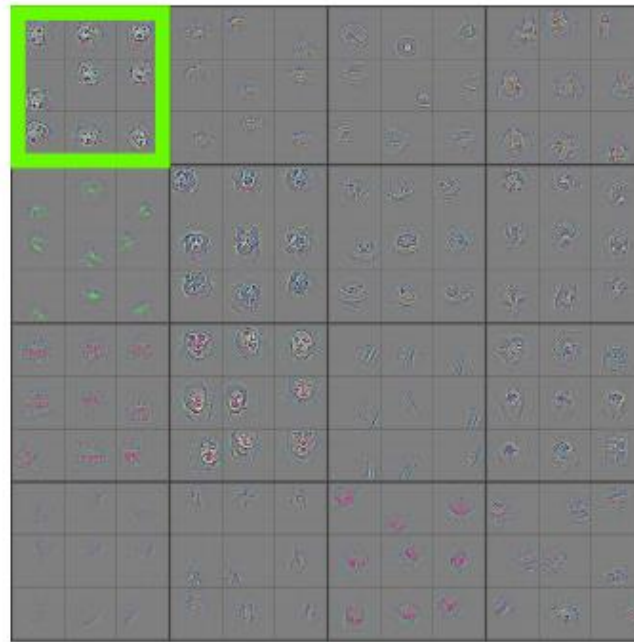
filter
response

Learned from data!

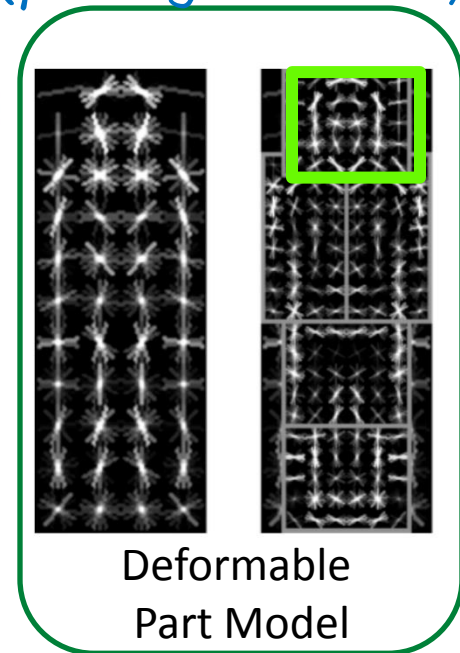
*Handcrafted
(partly learned)*



top 9 exciting patches
for each neuron



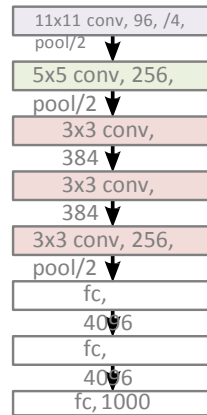
their deconvnet
reprojection



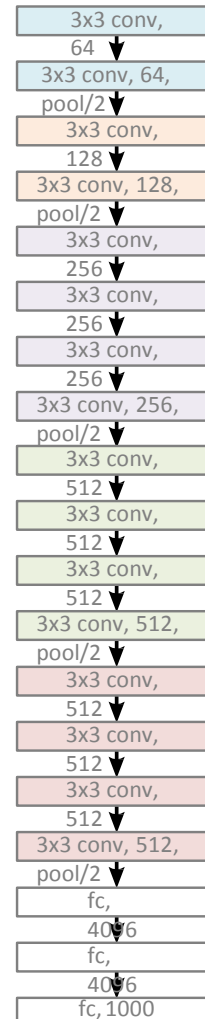
Deformable
Part Model

Deeper architectures

AlexNet, 8
layers
(ILSVRC
2012)



VGG, 19
layers
(ILSVRC
2014)



GoogLeNet, 22
layers
(ILSVRC 2014)



More layers, but smaller kernels

Ultra deep networks

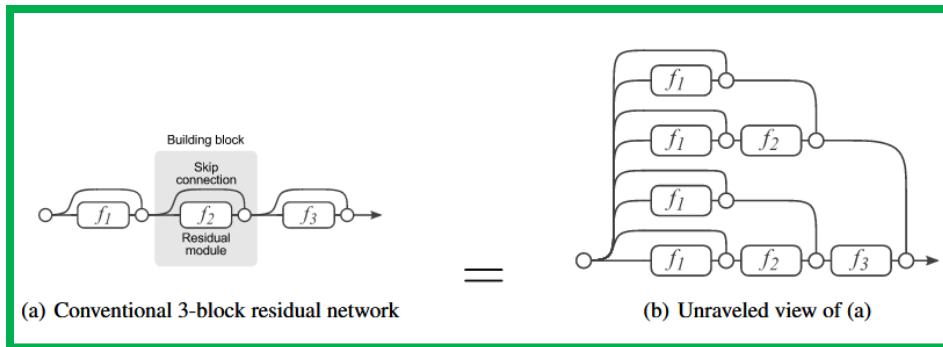
AlexNet
8 layers
(ILSVRC 2012)



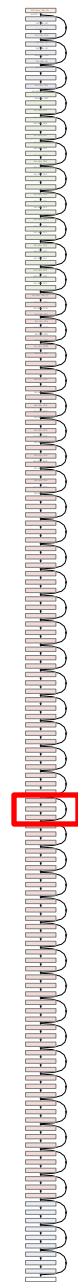
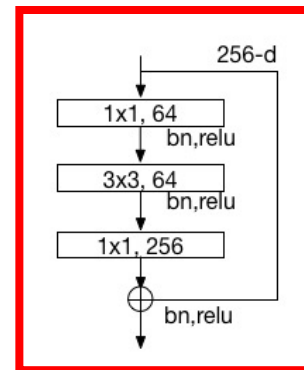
VGG
19 layers
(ILSVRC 2014)



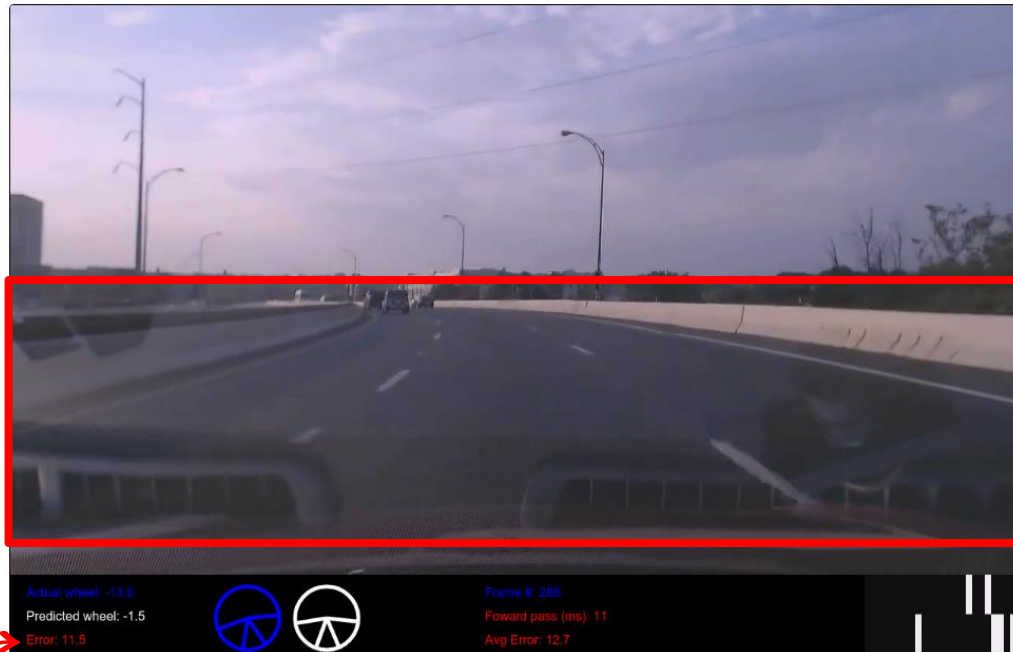
ResNet, 152
layers
(ILSVRC 2015)



*Interpretation as ensembles
of not-so-deep networks
(effective depth ≈ 20)*



Demo: learning to drive



Goal: steer the driving wheel following the road
Regression problem



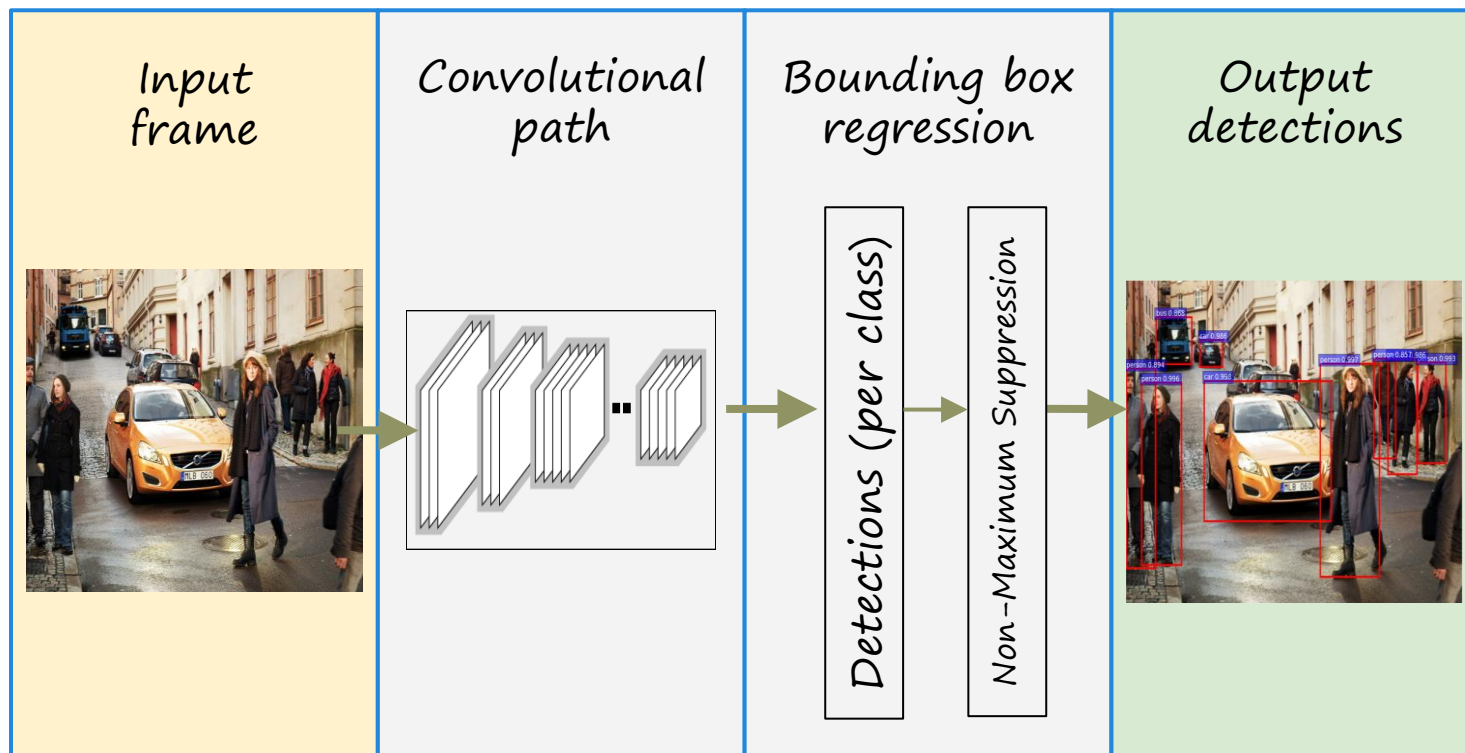
$Loss = |Angle1 - Angle2|$

Angle1 (human driver)

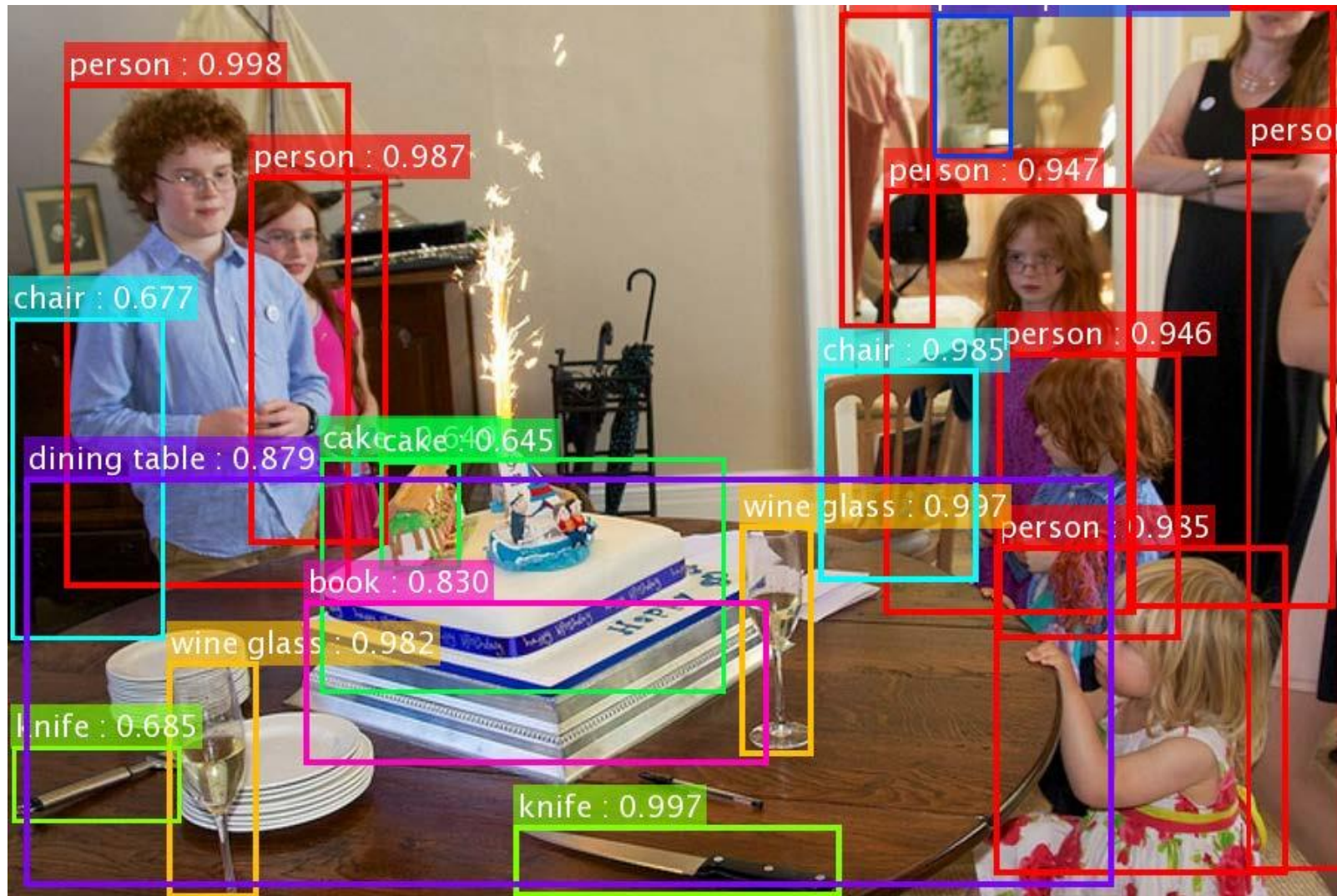
Angle2 (predicted by CNN)

Object detection

*Given an image detect the interesting objects
(localization+class)*



Object detection+classification



Object detection architectures

Very slow
 (each region separately)

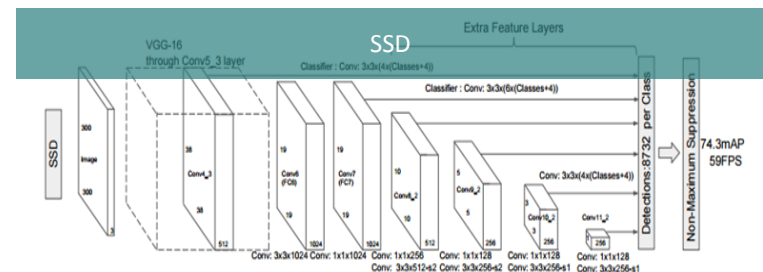
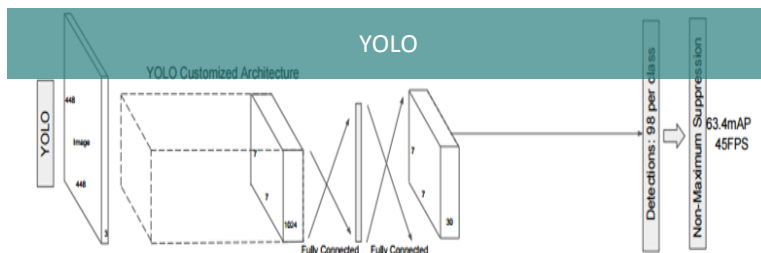
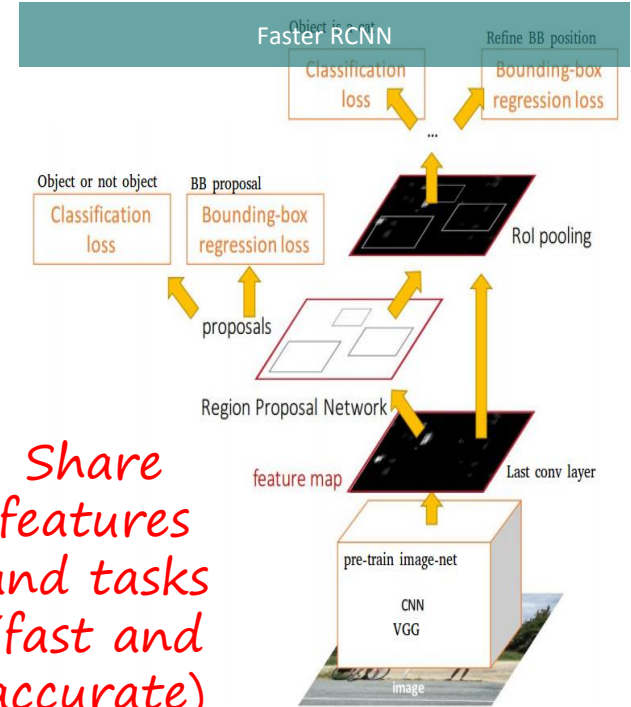
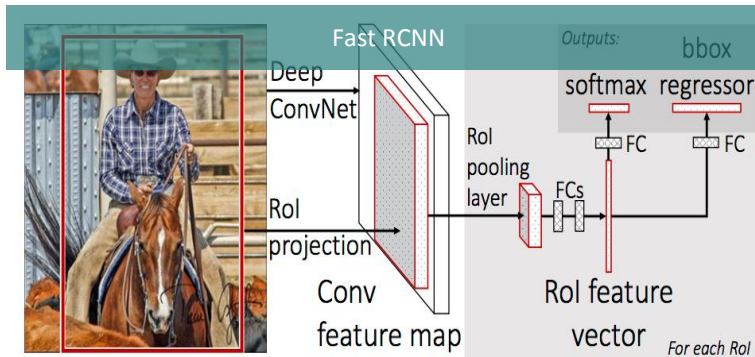
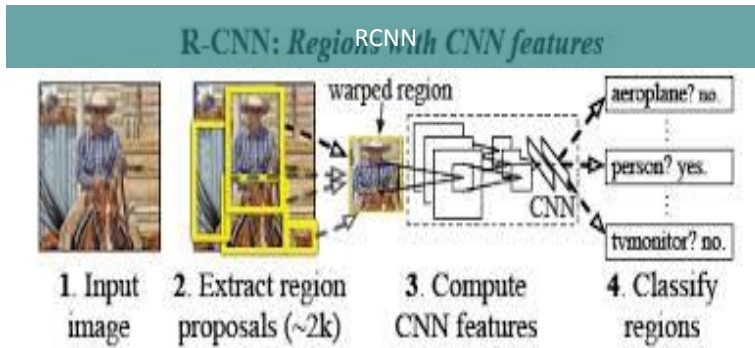


Image segmentation

Given an image classify each pixel with its category

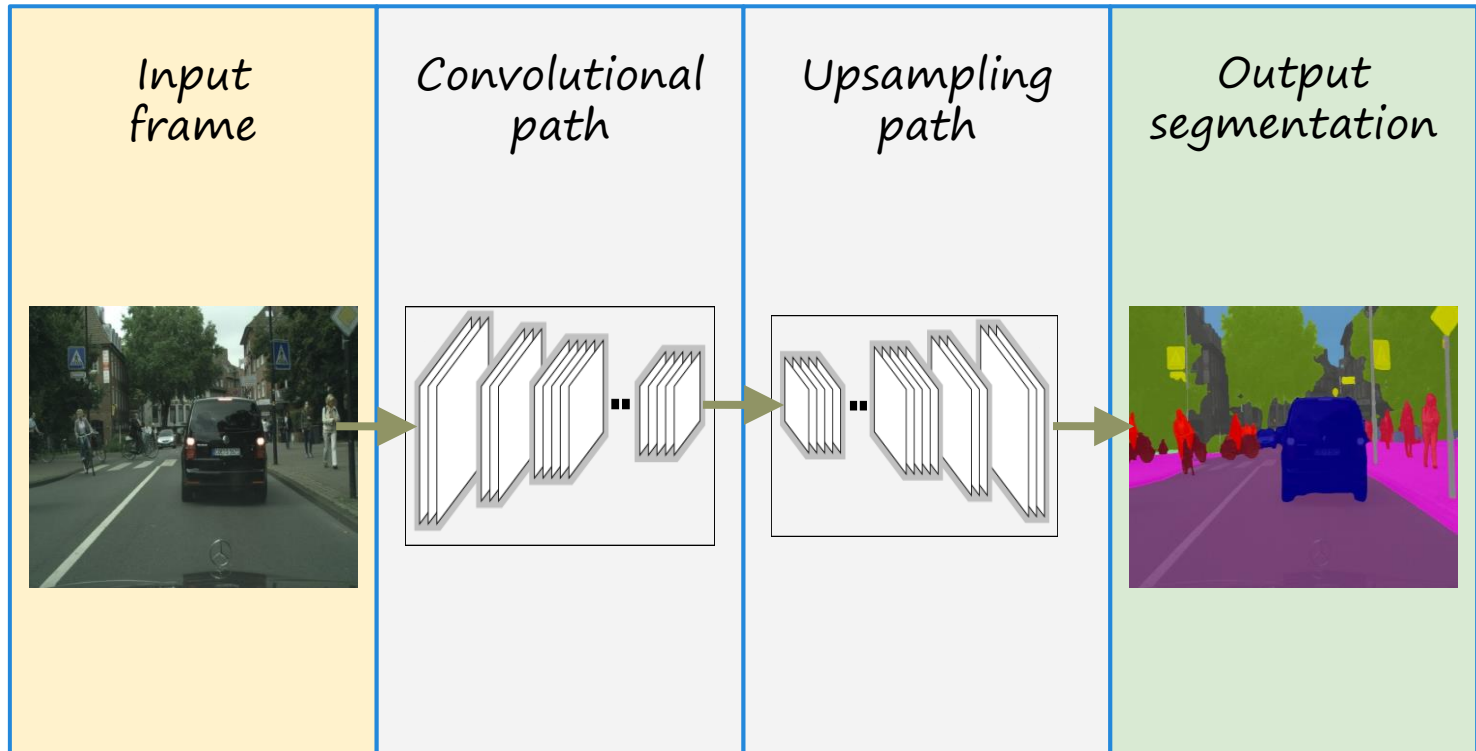
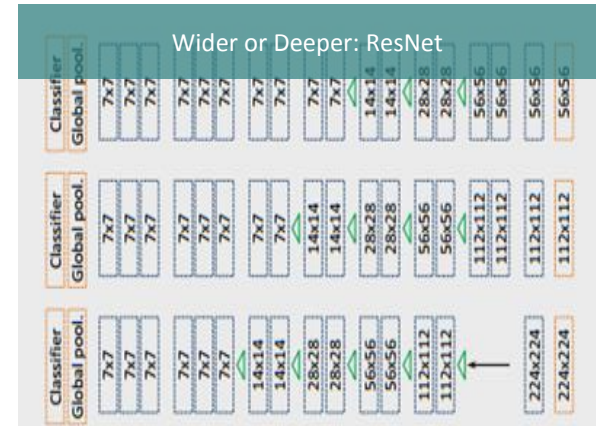
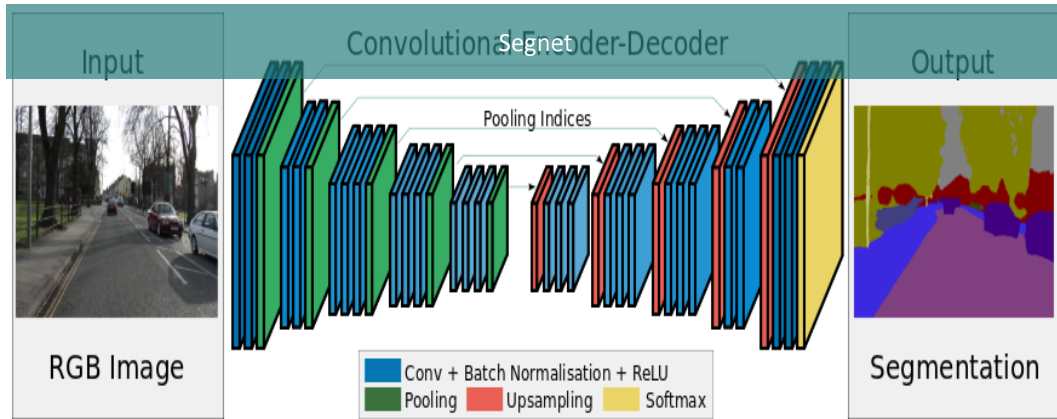
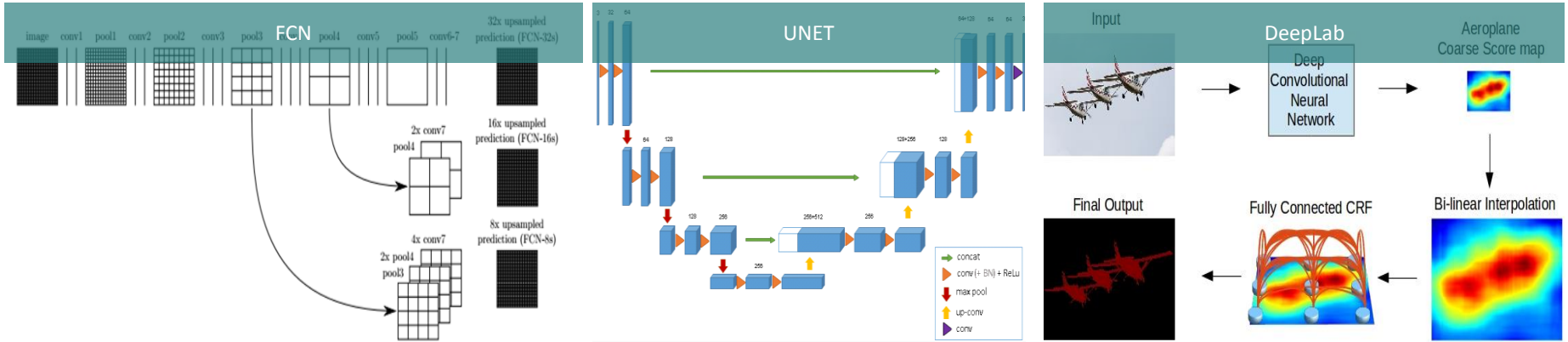


Image segmentation



Today's plan

- Machine learning
- Neural networks
- Deep learning in computer vision
- **Fun stuff**

Deep learning frameworks



Caffe

Developed by: Berkeley
Type: Imperative
Base language: C++
Interfaces: C/C++, Python, MATLAB
Multi-GPU: Yes



Developed by: NYU
Type: Imperative
Base language: LUA
Interfaces: C/C++, Lua,
Python
Multi-GPU: Yes



theano

Developed by: UdM (MILA)
Type: Symbolic
Base language: Python
Interfaces: Python
Multi-GPU: No

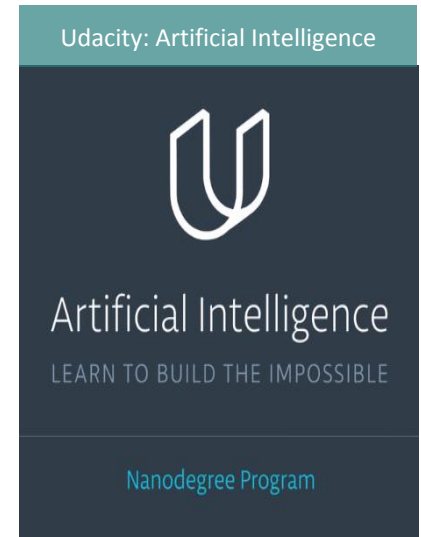
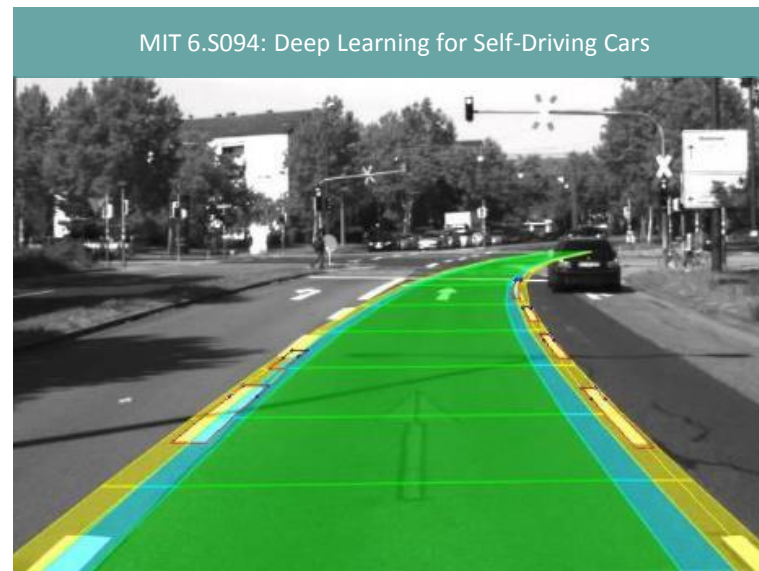
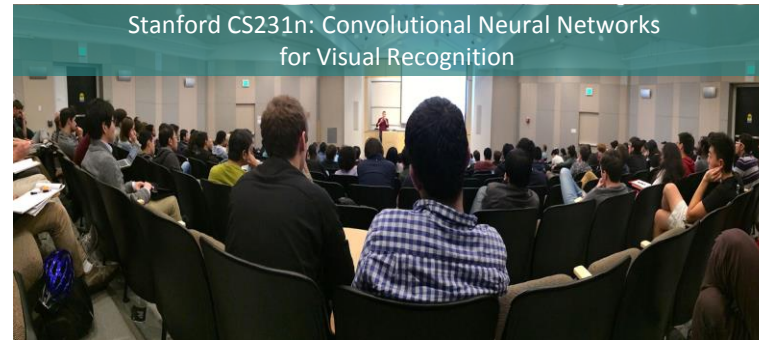
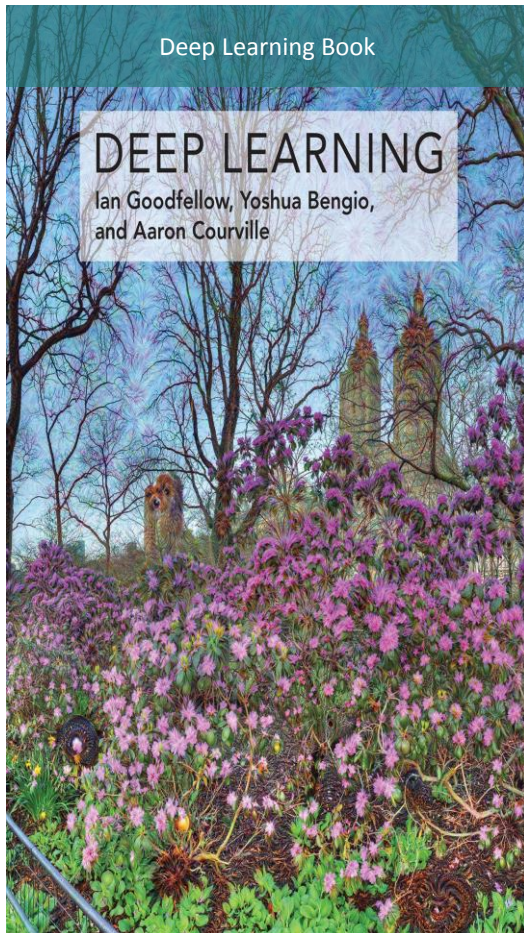


Developed by: Google
Type: Symbolic
Base language: C++
Interfaces: C++, Python
Multi-GPU: Yes

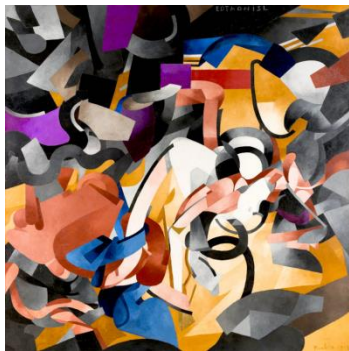


Developed by: UdM (MILA), Google
Type: Symbolic
Base language: Theano &
TensorFlow
Interfaces: Python
Multi-GPU: Yes

Learning deep learning



Style transfer



Content

A blue curved arrow pointing from the 'Content' image towards the final style-transferred image.

Style

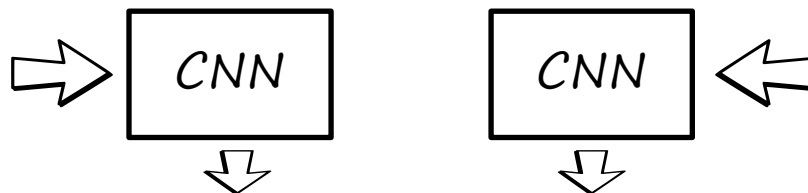
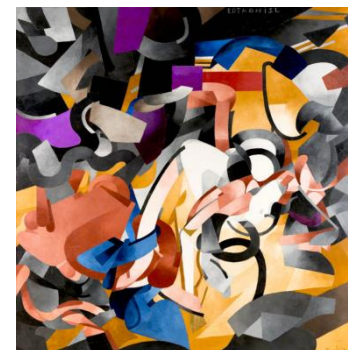
A green curved arrow pointing from the 'Style' image towards the final style-transferred image.

Style transfer

Content



Style



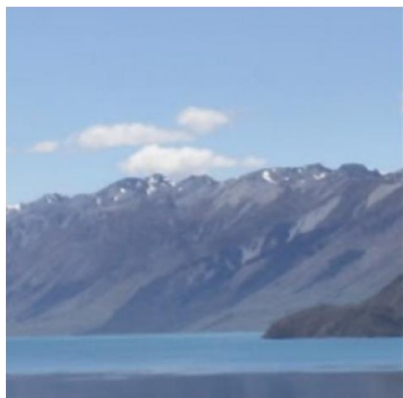
$$\mathbf{x}^* = \underset{\mathbf{x}}{\operatorname{argmin}} (\alpha \mathcal{L}_{\text{content}}(\mathbf{c}, \mathbf{x}) + \beta \mathcal{L}_{\text{style}}(\mathbf{s}, \mathbf{x}))$$

$$\mathcal{L}_{\text{content}}(\text{img}_1, \text{img}_2) \approx 0 \quad \Downarrow \quad \mathcal{L}_{\text{style}}(\text{img}_3, \text{img}_4) \approx 0$$

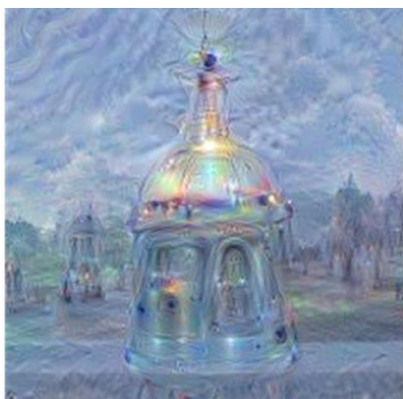


Optimize!!

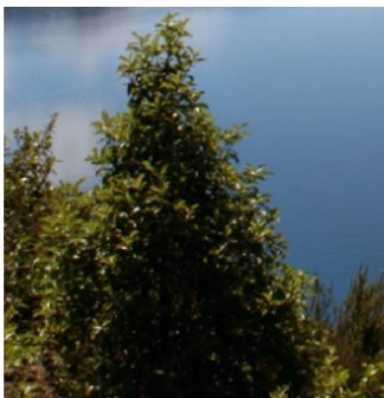
Deep dreams



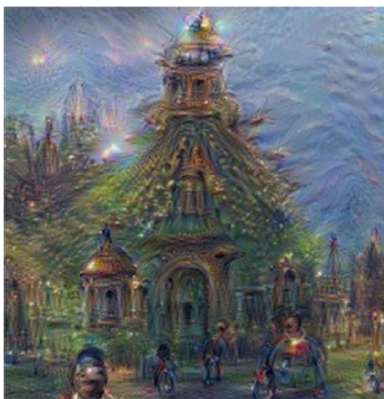
Horizon



Towers & Pagodas



Trees



Buildings



Leaves

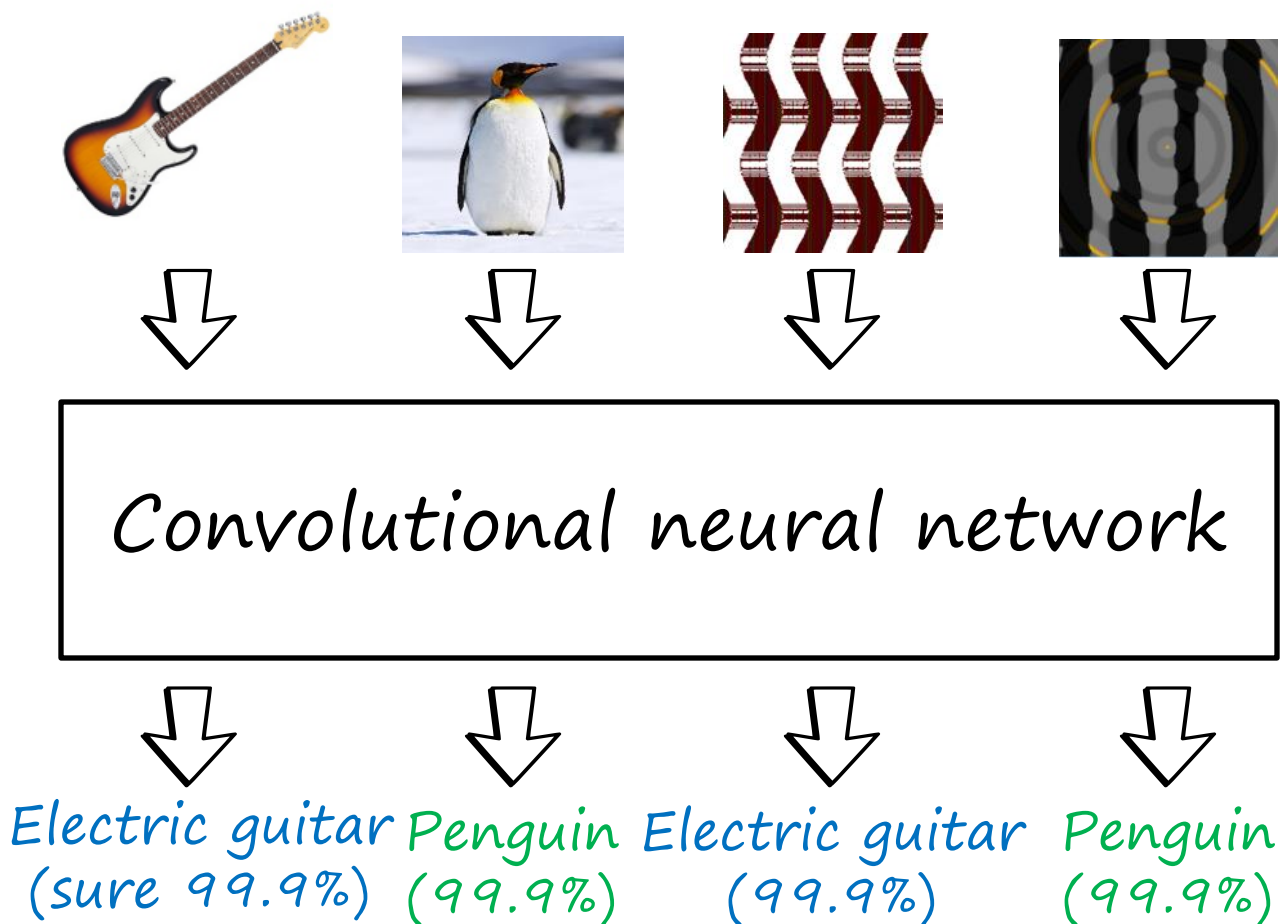


Birds & Insects

Deep dreams

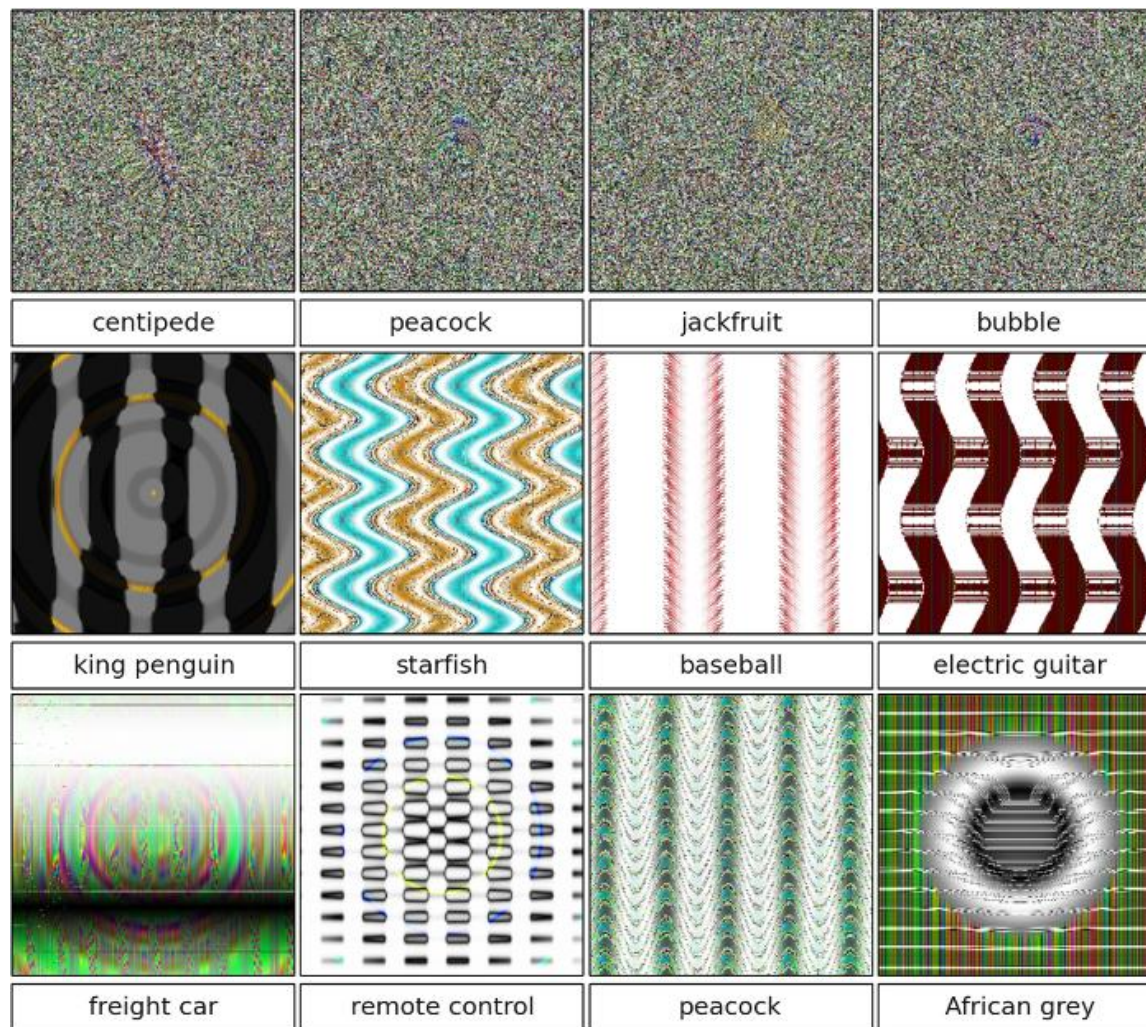


Are deep networks so smart?



Are deep networks so smart?

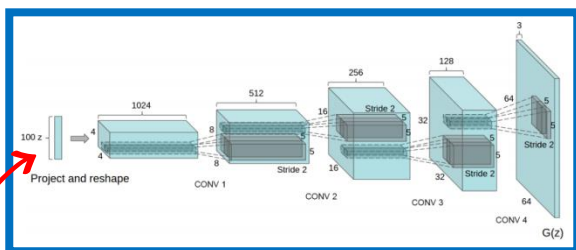
All 99.9% confidence!!



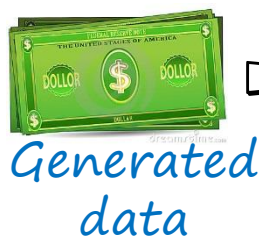
Networks that can imagine

Generative adversarial networks

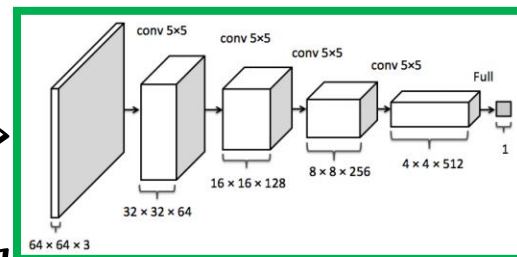
Generator



Random vector



Discriminator



Real or fake?



The game (encouraged by the loss functions):

- The generator has to fool the discriminator (by generating more realistic money)
- The discriminator has to improve to detect fake money
(other approaches: autoencoders, PixelCNNs, ...)

Goodfellow et al, Generative Adversarial Nets, 2014

Radford et al, Unsupervised Representation Learning with Deep Convolutional Generative Adversarial Networks, 2016

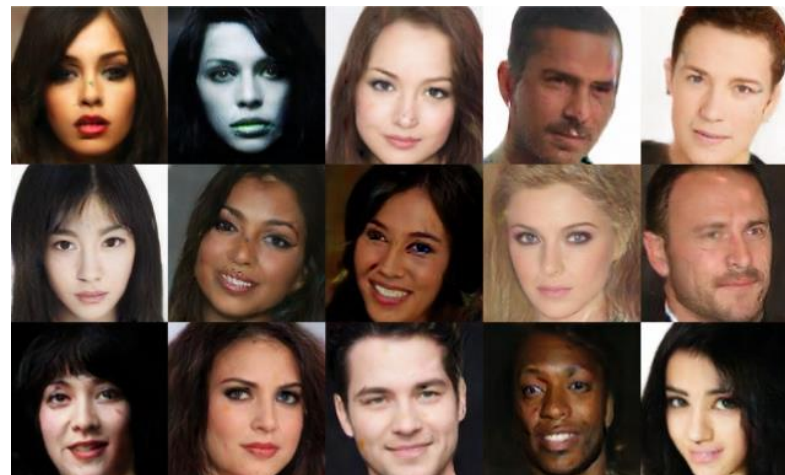
A good explanation <https://medium.com/@ageitgey/abusing-generative-adversarial-networks-to-make-8-bit-pixel-art-e45d9b96cee7>

Generative adversarial networks

Simulate face aging

Generate faces

0-18 19-29 30-39 40-49 50-59 60+



Interpolate faces

*They are not real people
(don't exist in the real world!!!)*

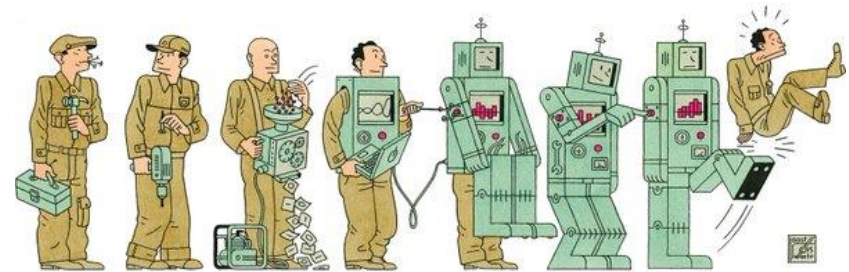


Today's plan

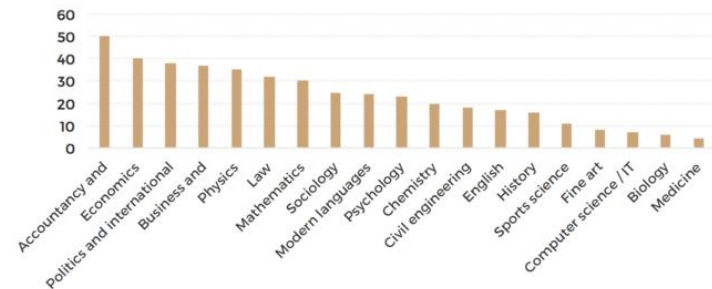
- Machine learning
- Neural networks
- Deep learning in computer vision
- Fun stuff
- **Some serious stuff**

Responsability: DL is a powerful tool

- Social implications
 - Jobs
 - Security and privacy
 - Military use
 - Ethics and values



% of jobs that could be replaced by automation



Frey & Osborne (2013) The future of employment: How susceptible are jobs to computerisation?



Existential risk and safe AI

- Serious concerns on AI's existential risk
 - Other risks: climate change, nuclear holocaust, misuse of nanotech., ...
- Action lines for safe AI
 - Open access to code, data and resources. Transparency in general
 - Education in machine learning
 - Differential privacy
 - Regulation
 - Human values in AI
- Some people take this very seriously
 - Future of Life Institute
 - Beneficial AI conference <https://futureoflife.org/bai-2017>
 - AI principles: <https://futureoflife.org/ai-principles>
 - Future of Humanity Institute, University of Oxford
 - Centre for the Study of Existential Risk, University of Cambridge



Learning and Machine
Perception (LAMP) team

<http://www.cvc.uab.es/lamp>

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Organitzadors:



Amb la col·laboració:

